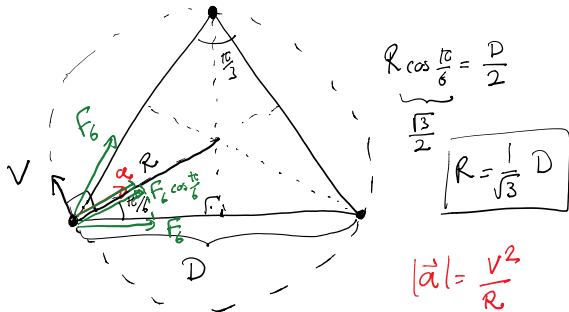
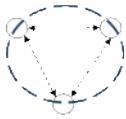


Assume that three planets each with the same mass $M/3$ form an equilateral triangle of side D . What should be their rotation **period** around their common center of mass (which is the center of the dashed circle in the figure) so that the system is in equilibrium. (This configuration is in general known as Klempler's rosette)



$$R \cos \frac{10}{6} = \frac{D}{2}$$

$$\frac{\sqrt{3}}{2}$$

$$R = \frac{1}{\sqrt{3}} D$$

$$|\vec{a}| = \frac{v^2}{R}$$

$$F_{\text{net}} = 2F_g \cos \frac{10}{6} = 2 G \frac{(M/3)(M/3)}{D^2} \frac{\sqrt{3}}{2}$$

$$F_{\text{net}} = \left(\frac{M}{3}\right) a$$

$$G \frac{M^2/9}{D^2} \sqrt{3} = \frac{M}{3} \frac{v^2}{D}$$

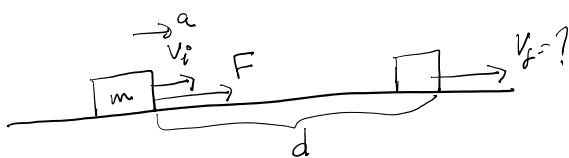
$$v^2 = 3 G \frac{M}{3D} \Rightarrow v = \sqrt{G \frac{M}{3D}}$$

$$T = \frac{2\pi R}{v} = \frac{2\pi D/\sqrt{3}}{\sqrt{G \frac{M}{3D}}} = \frac{2\pi D^{3/2}}{\sqrt{GM}}$$

$$[T] = \text{sec} = \frac{m^{3/2}}{\sqrt{\frac{m^2}{kg^2} kg kg^{1/2}}} = s \frac{m^{3/2}}{m kg^{1/2}} = s \frac{1}{kg^{1/2}}$$

1) $\text{Gnd } v$
2) Units
3) Limit

Work and Kinetic Energy



$$a = \frac{F}{m}$$

$$v_f = v_i + at$$

$$+ = \frac{v_f - v_i}{t}$$

$$\overline{\left(\frac{F}{m}\right)}$$

$$d = v_i t + \frac{1}{2} a t^2$$

$$= v_i \frac{(v_f - v_i)}{\frac{F}{m}} + \frac{1}{2} \left(\frac{F}{m}\right) \frac{(v_f - v_i)^2}{\left(\frac{F}{m}\right)^2}$$

$$\frac{F}{m} d = v_i (v_f - v_i) + \frac{1}{2} (v_f - v_i)^2$$

$$F d = m (v_f - v_i) \left[v_i + \frac{1}{2} v_f - \frac{1}{2} v_i \right]$$

$$F d = m (v_f - v_i) \frac{(v_i + v_f)}{2} = \underbrace{\frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2}_K$$

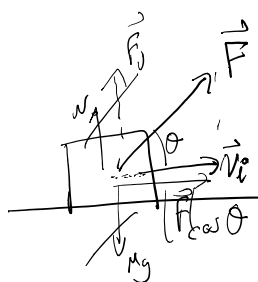
$$K = \frac{1}{2} m v^2$$

$$W = F d$$

$$\Delta K = K_f - K_i = F d$$

$$\Delta K = W$$

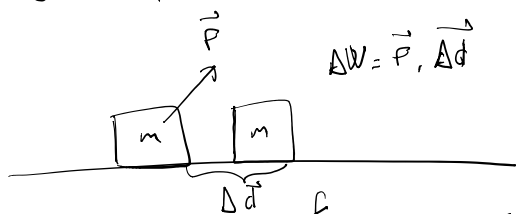
Work-Energy theorem



$$W = \vec{F} \cdot \vec{d}$$

$$\Delta K = W$$

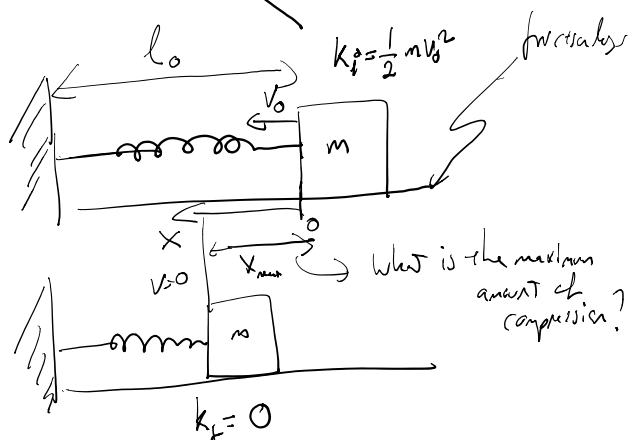
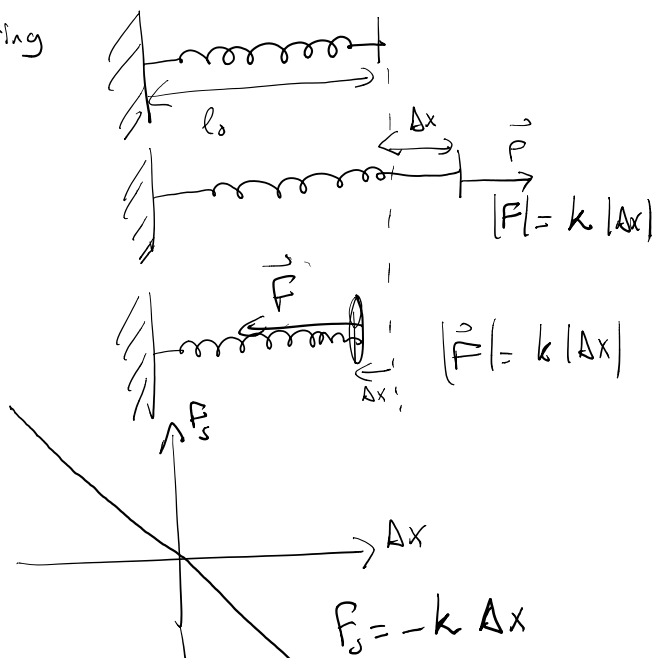
What if the force is not a constant?



$$\Delta W = \vec{F} \cdot \Delta \vec{d}$$

$$W = \int_i^f \vec{F} \cdot d\vec{\ell} \quad (\text{line integral})$$

Ideal Spring



$$\Delta K = K_f - K_i = -\frac{1}{2} m v_0^2 = W$$

$$= \int \vec{F}_s \cdot d\vec{l}$$

$$= - \int_0^{x_{max}} kx \, dx$$

$$-\frac{1}{2} m v_0^2 = -k \int_0^{x_{max}} x \, dx$$

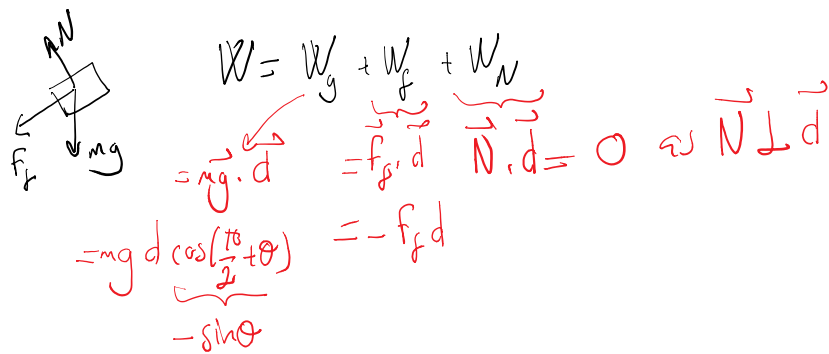
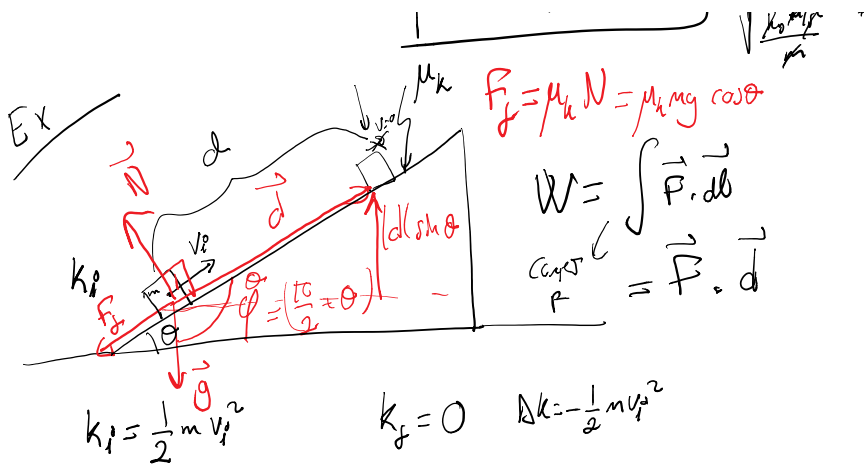
$$\frac{1}{2} m v_0^2 = k \frac{x_{max}^2}{2}$$

$$x_{max} = \sqrt{\frac{m}{k}} v_0$$

$$[x_{max}] = m$$

$$\sqrt{\frac{kg}{\rho_0 \omega^2 x}}$$

$$\mu_k F_f = \mu_k N = \mu_k m g \cos \theta$$



$$W = -mg d \sin \theta - F_f d$$

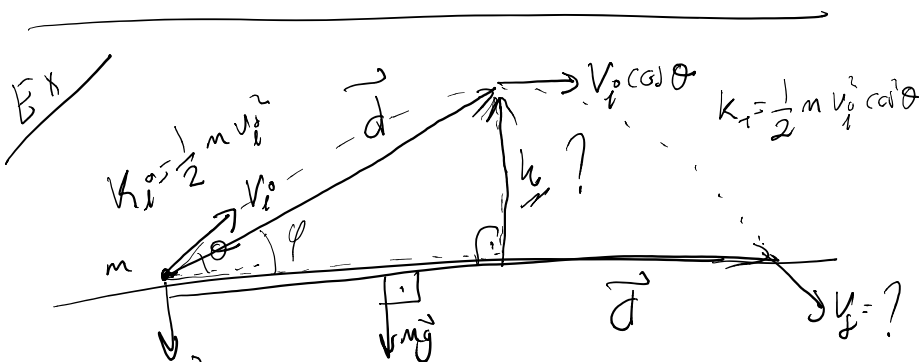
$$\Delta K = -\frac{1}{2} m v_i^2 = (-mg \sin \theta - F_f) d$$

$$\frac{1}{2} m v_i^2 = (mg \sin \theta + \mu_k mg \cos \theta) d$$

$$\frac{1}{2} v_i^2 = g d (\sin \theta + \mu_k \cos \theta)$$

$$d = \frac{v_i^2}{2g (\sin \theta + \mu_k \cos \theta)}$$

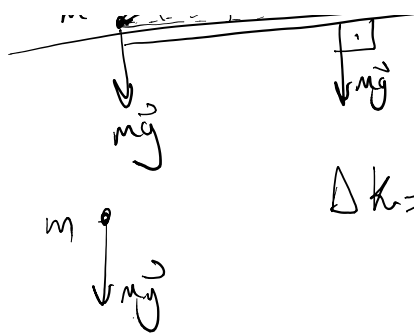
- 1) Good
2) $\frac{v_i^2}{2g}$ ✓
3) $v_i \rightarrow 0 \rightarrow d \rightarrow 0$ ✓



$$K_f - K_i = \vec{F} \cdot \vec{d}$$

$$= -mg h$$

1 / 2 / 2 / 1 / 1



$\vec{F} \rightarrow y_f = ?$

$$\begin{aligned}\Delta K &= \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2 = W \\ &= \int \vec{F} \cdot d\vec{b} \\ &= \vec{F} \cdot \vec{d} \\ &= \underbrace{m\vec{g} \cdot \vec{d}}\end{aligned}$$

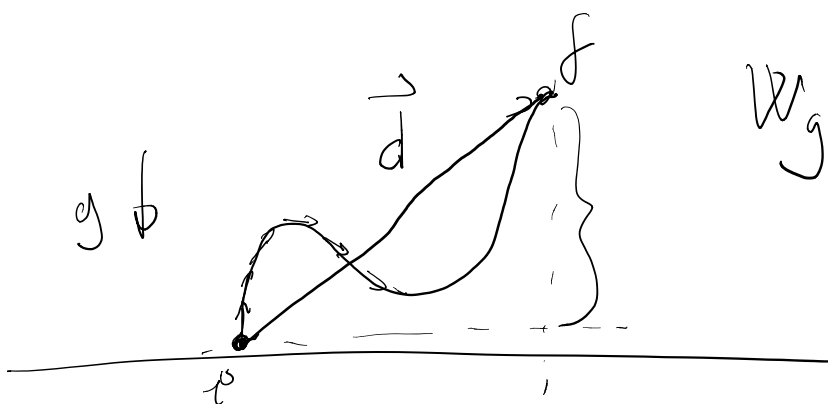
$$v_i^2 = v_f^2 \Rightarrow \boxed{v_f = v_i}$$

$$\frac{1}{2}mv_i^2(\cos\theta - 1) = mgh$$

$$h = \frac{v_i^2}{2g}(1 - \cos\theta)$$

$$\boxed{h = \frac{(v_i \sin\theta)^2}{2g}}$$

$K \rightarrow \text{scalar!}$



$$\begin{aligned}W_g &= \int_i^f \vec{F} \cdot d\vec{b} \\ &= \underbrace{(m\vec{g})}_f \cdot \underbrace{\int_i^f d\vec{b}}_d \\ &= m\vec{g} \cdot \vec{d}\end{aligned}$$

$$\begin{aligned}W_g &= m\vec{g} \cdot \vec{d} \\ &= -mgh\end{aligned}$$

$$\Delta K = W$$

$$\Delta K = \underbrace{W_g}_{\text{gravity}} + W_F$$

$$-mgh$$

$$\Delta K + mgh = W_f$$

$$\left(\frac{1}{2} m v_f^2 + \underbrace{mgh_f} \right) - \left(\frac{1}{2} m v_i^2 + mgh_i \right) = W_f$$

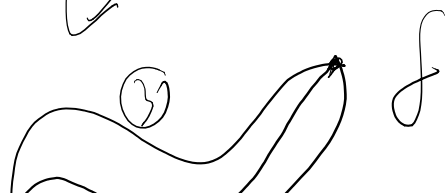
$$U_g = mgh \Rightarrow \text{Gravitational Potential energy!}$$

$$E = K + U_g$$

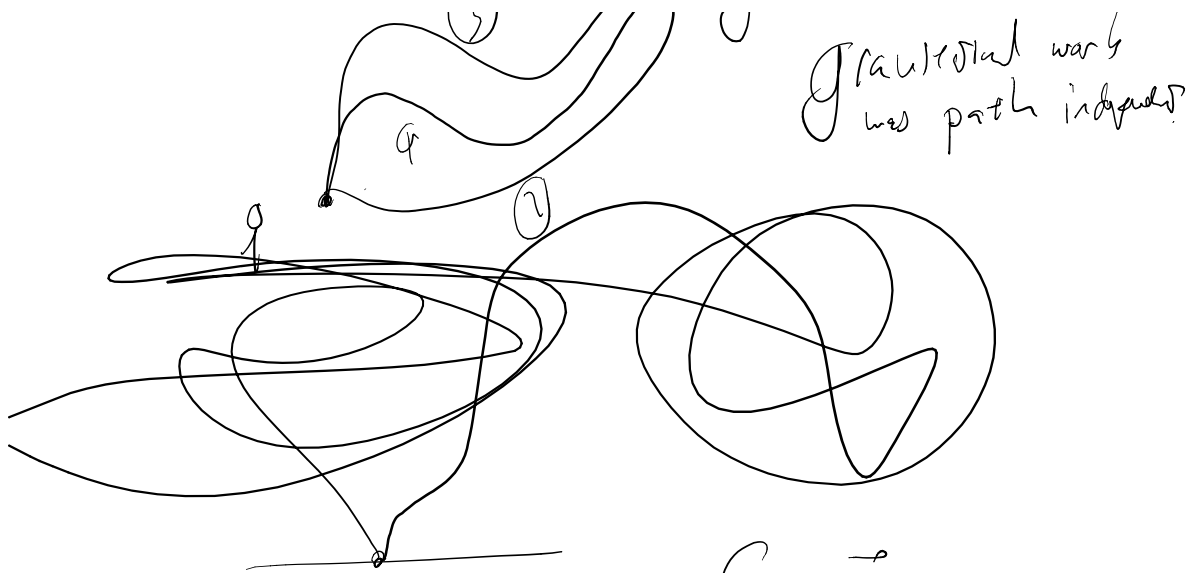
$$\boxed{\Delta E = W_f}$$

Can we define a potential energy for the other forces as well?

$$W = \int \vec{F} \cdot d\vec{r} = -mg(h_f - h_i) = -(U_{g(f)} - U_{g(i)})$$

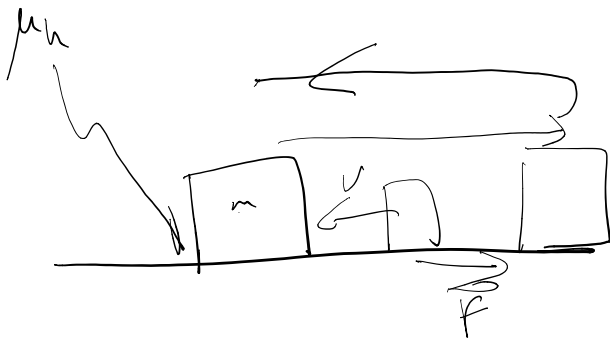


Gravitational work is path independent



$$\oint \vec{F}_g \cdot d\vec{s} = 0$$

For any force if $\oint \vec{F} \cdot d\vec{s} = 0$
a potential energy can be defined!



$$\vec{v} \cdot \vec{F} < 0$$

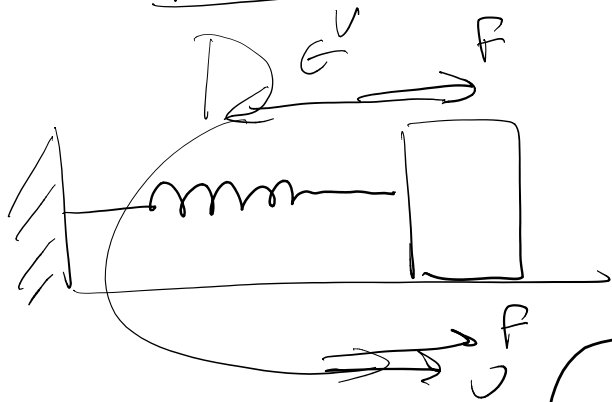
$$\oint \vec{F}_f \cdot d\vec{s} < 0 \neq 0$$

Friction is path dependent

\Rightarrow No potential possible

Nonconservative force (Dissipative force)

Nonconservative force (Dissipative force)



\vec{v}, \vec{F} changes sign

$$\oint \vec{F} \cdot d\vec{s} = 0$$

Conservative force

$$U_s = \frac{1}{2} k x^2$$

compression
or stretching!

$$E = K + U_g + U_s + \dots$$

↑
mechanical
energy

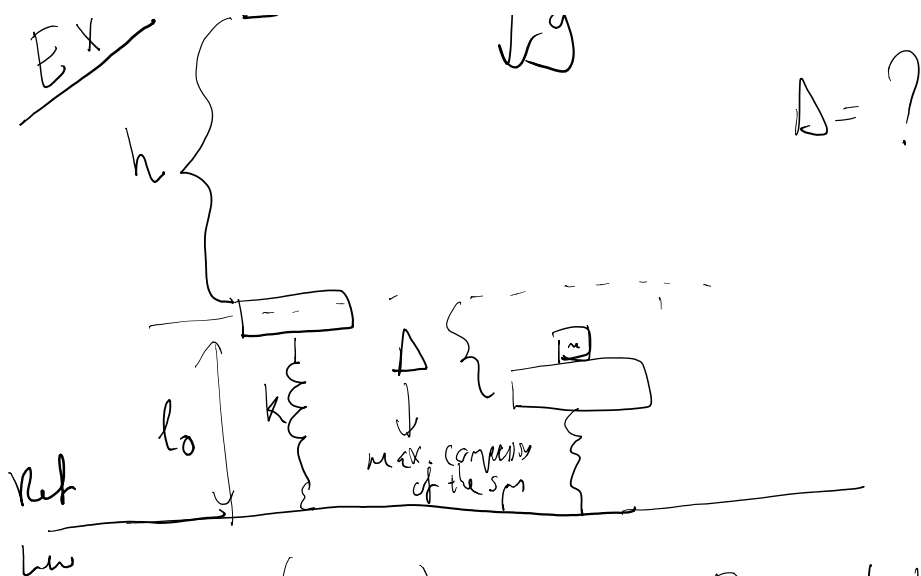
$$\Delta E = W_{n.c.}$$

E_x
h

droppy
m

kg

$$\Delta = ?$$



$$E_i = mg(h + l_0)$$

$$E_f = \frac{1}{2} k \Delta^2 + mg(l_0 - \Delta)$$

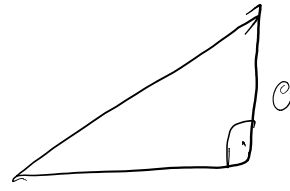
$$mgh + \cancel{mg l_0} = \frac{1}{2} k \Delta^2 + \cancel{mg l_0} - mg \Delta$$

$$mgh = \frac{1}{2} k \Delta^2 - mg \Delta$$

$$0 = \frac{k}{2} \Delta^2 - mg \Delta - mgh$$

$$\Delta = \frac{mg}{k} \mp \frac{1}{k} \sqrt{m^2 g^2 + 4 \frac{k}{2} mgh}$$

$$= \frac{mg}{k} \mp \sqrt{\left(\frac{mg}{k}\right)^2 + 2 \frac{mg}{k} h}$$



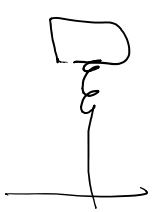
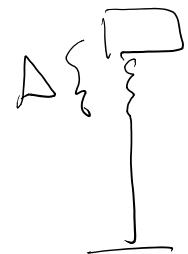
$$\frac{mg}{k}$$



$$\Delta = \frac{mg}{k} + \sqrt{\left(\frac{mg}{k}\right)^2 + 2 \frac{mg}{k} h}$$

$$h \rightarrow 0$$

$$\Delta = ?$$



$$mg \Delta = \frac{1}{2} k \Delta^2$$

$$\frac{2mg}{k} = \Delta$$

Nov 14-18

No Phys 101 classes

We'll have make-up lectures

NAME:	
STUDENT NO:	
SIGNATURE:	
DEPARTMENT	
SECTION	

PHYSICS 101- Instructor: M. Özgür OKTEL- 2016

QUIZ-12

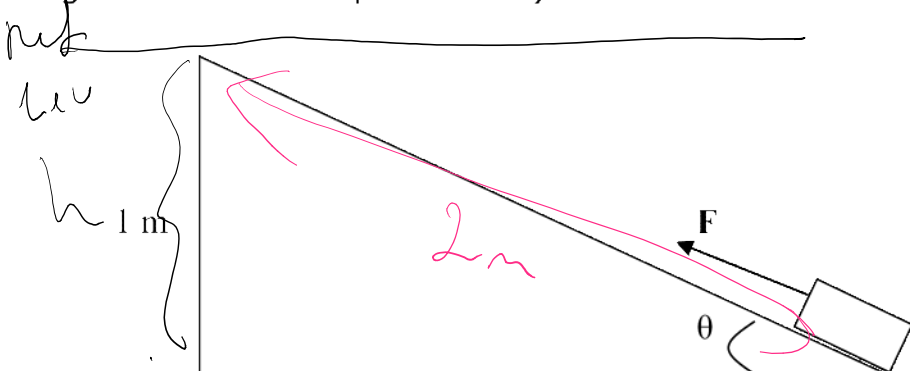
A mass $m=1\text{kg}$ is at the bottom of an inclined plane as shown in the figure.

What is the minimum work that is needed to be done by the force \vec{F} , (directed as shown in the figure) to get the mass to the top of the inclined plane if

a) There is no friction between the mass and the plane.

b) The friction coefficient between the mass and the plane is $\mu = 1/\sqrt{3}$.

(Assume $g = 10 \text{ m/s}^2$, the inclination of the plane is $\theta = 30$ degrees, and the height of the inclined plane is 1m)



$$\Delta E =$$

$$E_f - E_i =$$

$$K_f + U_f - (K_i + U_i) = 0 \text{ for minimum work}$$

$$a) \quad E_i = -mgh + 0 = -1 \text{ kg} \cdot 10 \text{ m/s}^2 \cdot 1 \text{ m} = -10 \text{ J}$$

$$E_f = 0 + 0 = 0$$

$$\Delta E = E_f - E_i$$

—

W

W

$$\gamma = \underline{\underline{W}}$$

h

$$\frac{m^3}{s^2}$$

—
ade

$$- \overbrace{105.11}$$

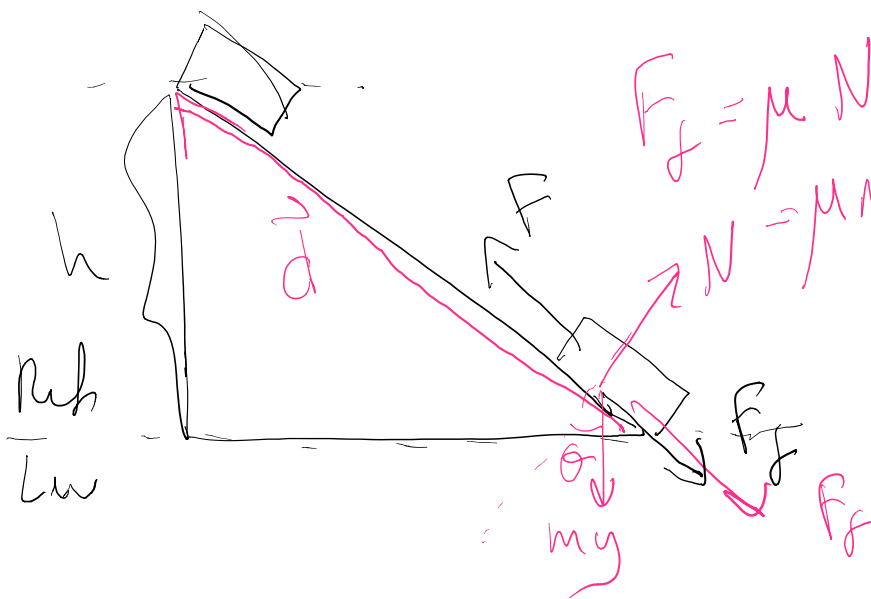
• δ $\cup - \cup - \cup$

$$\delta = 0 - (-10)$$

$$W = 10 \text{ J}$$

$$\Delta E = W$$

⑥



$$F_f = \mu N$$

$$N = \mu mg \cos \theta$$

$$E_i = U_i + K_i$$

$$= 0 + 0 =$$

$$E_f = mgh + K_f$$

$$\Delta E = E_f - E_i =$$

$$\Delta E = W$$

$$= W_F + W_\mu$$

work done

$$W_\mu = \vec{F}_f \cdot \vec{d} = -\mu mg \cos \theta d$$

$$= \boxed{10 \text{ Jals}}$$

$$\begin{aligned} & \text{O J} \\ & = 10 \text{ J} \end{aligned}$$

$$10 \text{ J}$$

by function

$$= -\frac{1}{\sqrt{8}} \cdot 10 \cdot \frac{\sqrt{3}}{2} =$$

$$\Delta E = W_f + W_g$$

$$10 = W_f - 10 \Rightarrow$$

$$W_f =$$

6

$$[Energy] = Joules = kg \cdot m^2 / s^2$$

Calories

kWh

Define Power

$$P = \frac{dE}{dt} \Rightarrow [P] = \frac{[E]}{s} = \frac{kg \cdot m^2}{s^3}$$

- 10 J

20 J

→

$y \text{ m}^2/\text{s}^2$

S

2,

$$P = \frac{dW}{dt} \Rightarrow \text{kg} \cdot \text{m}^2 \cdot \text{s}^{-3} = \text{Watt}$$

Horse power ≈ 750 Watt.

Power

Energy

$$K = \frac{1}{2} m v^2$$

$$P = \frac{d}{dt} \left(\frac{1}{2} m v^2 \right) = \frac{m}{2} \frac{d}{dt} (v^2) = \frac{m}{2} \frac{d}{dt} (v \cdot v) = v \cdot \frac{d}{dt} v = v \cdot \frac{d}{dt} \vec{v}$$

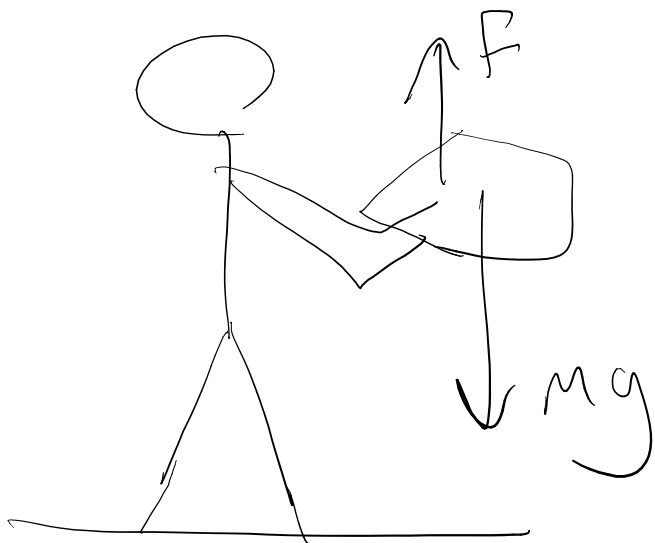
$$P = \vec{F} \cdot \vec{v}$$

$$\frac{m^2}{s^3}$$

$$-t$$

$$-v \frac{dv}{dt}$$

$$a = Fv$$



$$W = F \cdot d$$

Summary so far

$$\Delta E = W$$



$$E = K + U$$

$$K = \frac{1}{2}mv^2$$

11

11



$$W = \int F \cdot dx$$

Constant force

- 0

→

↪
ds

→
d

Can have diff sources

constant force

All conservative forces can be expressed in terms of a potential.

$$U_s = \frac{1}{2} k x^2 \quad (\text{spring})$$

$$U_g = m g h \quad \left(\begin{array}{l} h \text{ is the} \\ \text{above a} \end{array} \right.$$

We derived this for $\vec{F}_g = m \vec{g}$
only an approx.

$$\vec{F}_g = G \frac{M_E m}{r^2}$$

e highest
ref. level)

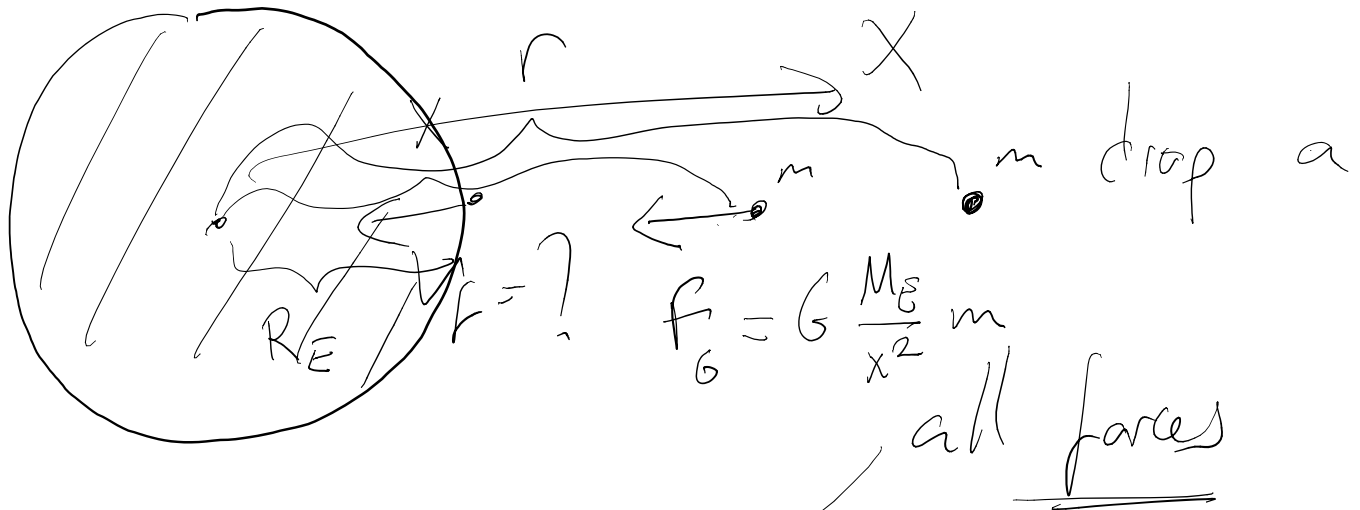
→
G
—
estimation

R → distance,

$$F_G = G \frac{M_E m}{R^2}$$

Potential energy for gravitation,

Ex



$$\Delta K = W$$

$$= \int_1^2 \vec{F} \cdot d\vec{b} = \int_r^{R_E} G \frac{M_E}{x^2} m dx$$

$$= M_E m \left[-\frac{1}{x} \right]_r^{R_E}$$

$R \rightarrow$ distance
from the
center of the
earth.

net
force distance r

$$\int \frac{1}{x^2} dx = -\frac{1}{x}$$

(dx)

$$= -G M_E m \left[\frac{-1}{x} \right]_r$$

$$K_f - K_i = -G M_E m \left[\frac{1}{r} - \frac{1}{R_E} \right]$$

$$\frac{1}{2} m v_f^2 = -G M_E m \left[\frac{1}{r} - \frac{1}{R_E} \right]$$

$$\frac{1}{2} m v_f^2 - G \frac{M_E m}{R_E} = -G \frac{M_E m}{r}$$

↓

K_f

U_G

m_1

m_2

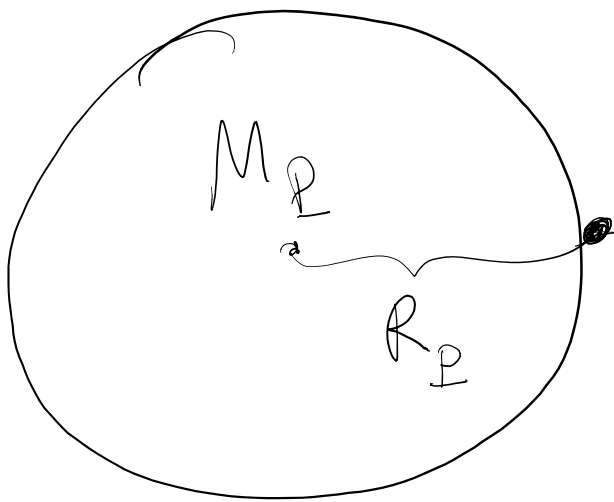
→]

] →

→]

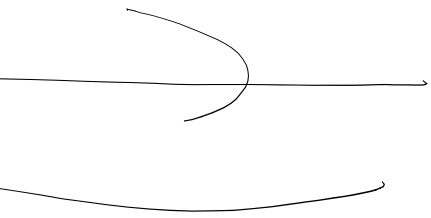
$$U_G = -G \frac{m_1 m_2}{r}$$

where should v
so that the
can



$$E_1 = \frac{1}{2} m v_e^2 - G \frac{M_P m}{R_P}$$

1st be
space
escape?



$$E_f = \cancel{M_g} - G \frac{M_E m}{\infty}$$

$a \quad o$

$$\hat{E}_f = 0$$

$$E_i = E_f$$

$$\frac{1}{2} m v_e^2 - G \frac{M_E m}{R_E} = 0$$

$$v_e = \sqrt{2 G \frac{M_E}{R_E}}$$

