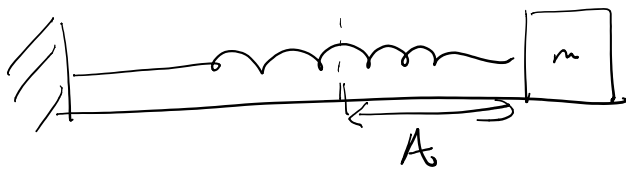
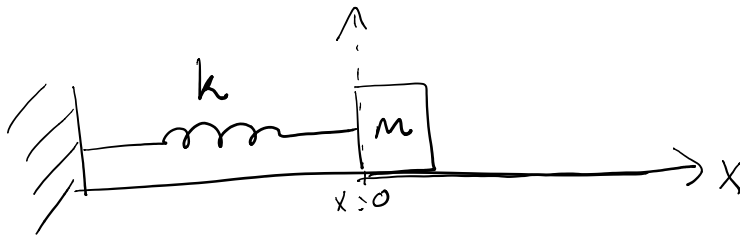
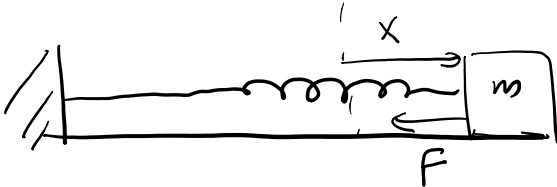


# Oscillations



for the system go



$$F = -kx$$

$$F = ma$$

$$-kx = m \frac{d^2x}{dt^2}$$

$$\boxed{\frac{d^2x}{dt^2} = -\frac{k}{m}x}$$

By inspection  $x(t) = C_1 \sin(\omega t) + C_2 \cos(\omega t)$

$$\frac{dx}{dt} = v(t) = \omega C_1 \cos(\omega t) - \omega C_2 \sin(\omega t)$$

$$\begin{aligned} \frac{d^2x}{dt^2} &= -\omega^2 C_1 \sin(\omega t) - \omega^2 C_2 \cos(\omega t) \\ &= -\omega^2 [C_1 \sin(\omega t) + C_2 \cos(\omega t)] \end{aligned}$$

$$\rightarrow -\omega^2 [C_1 \sin(\omega t) + C_2 \cos(\omega t)] = -\frac{k}{m} [C_1 \sin(\omega t) + C_2 \cos(\omega t)]$$

$$\rightarrow -\omega^2 [C_1 \sin(\omega t) + C_2 \cos(\omega t)] = -\frac{1}{m} [C_1 \sin(\omega t) + C_2 \cos(\omega t)]$$

$$\boxed{\omega = \sqrt{\frac{k}{m}}} \quad \begin{array}{l} \text{(Angular)} \\ \text{Frequency of oscillation} \end{array}$$

Now I know the solution is

$$x(t) = C_1 \sin\left(\sqrt{\frac{k}{m}}t\right) + C_2 \cos\left(\sqrt{\frac{k}{m}}t\right)$$

$$\begin{array}{l} C_1 = ? \\ C_2 = ? \end{array}$$

$$x(t=0) = A$$

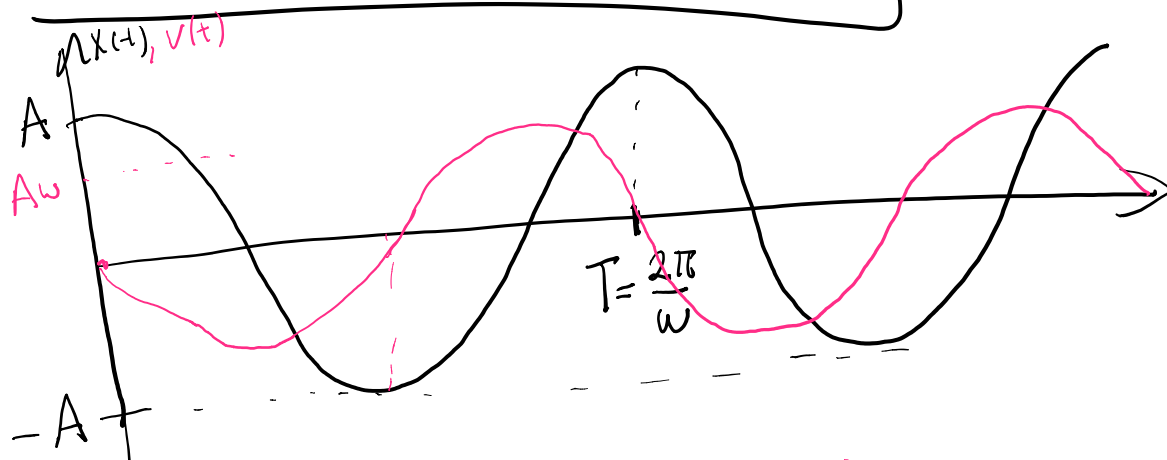
$$v(t=0) = 0$$

$$C_1 \underbrace{\sin(0)}_0 + C_2 \underbrace{\cos(0)}_1 = A \Rightarrow \boxed{C_2 = A} \quad \checkmark$$

$$v(t=0) = \omega C_1 \underbrace{\cos(0)}_1 - \omega C_2 \underbrace{\sin(0)}_0 = 0$$

$$\boxed{C_1 = 0} \quad \checkmark$$

$$\boxed{x(t) = A \cos\left(\sqrt{\frac{k}{m}}t\right)} \quad \omega = \sqrt{\frac{k}{m}}$$



$$-A \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---} \quad \text{---}$$

$$V(t) = -A\omega \sin(\omega t)$$

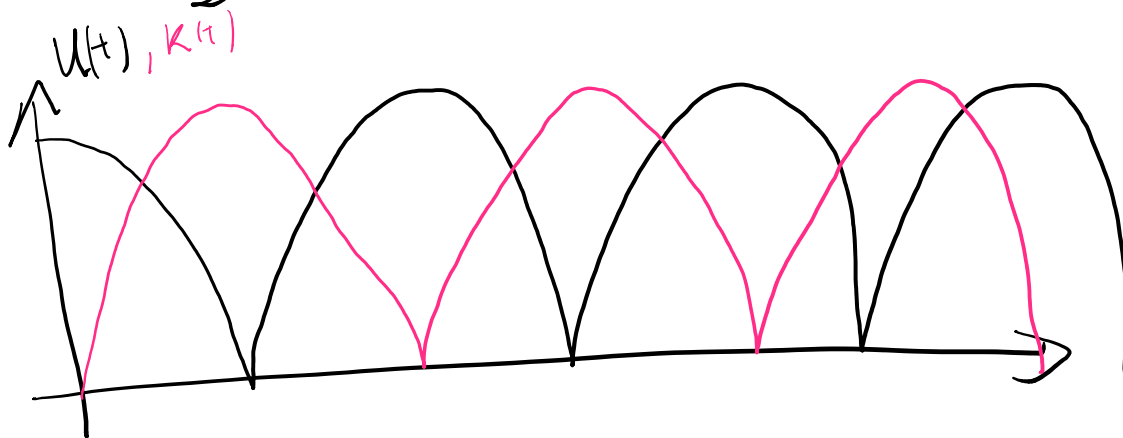
$$K(t) = \frac{1}{2} m \dot{V}(t)^2 = \frac{1}{2} m A^2 \omega^2 \sin^2(\omega t) = \frac{1}{2} k A^2 \sin^2(\omega t)$$

$$U(t) = \frac{1}{2} k x(t)^2 = \frac{1}{2} k A^2 \cos^2(\omega t)$$

$$E = K(t) + U(t)$$

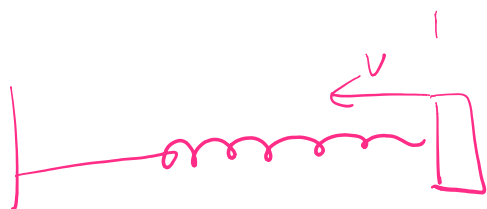
$$= \frac{1}{2} k A^2 \sin^2(\omega t) + \frac{1}{2} k A^2 \cos^2(\omega t)$$

$$= \frac{1}{2} k A^2 (\sin^2(\omega t) + \cos^2(\omega t)) = \frac{1}{2} k A^2$$



$$U = \frac{1}{2} k A^2$$

$$K = 0$$



$$U = 0$$

$$K = \frac{1}{2} k A^2$$

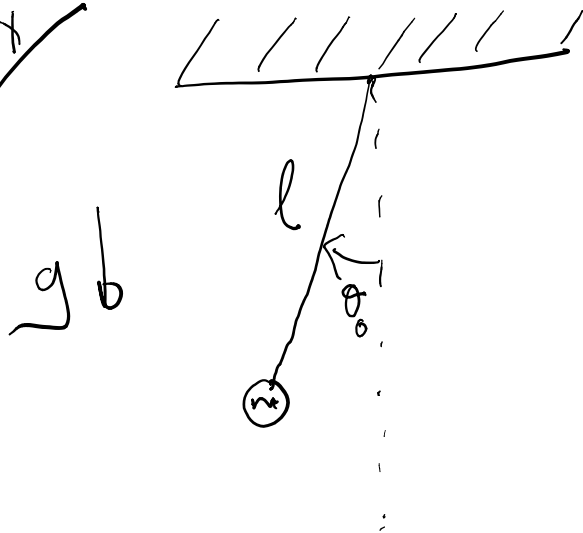
Energy oscillates between kinetic and potential forms.

$$\omega = \sqrt{\frac{k}{m}} \quad , \quad \underline{\text{is independent of Amplitude!}}$$

If  $T$  (or  $\omega$ ) of an oscillator is independent of its amplitude it is called a Harmonic Oscillator.

Harmonic oscillations are good models for almost all oscillations when the amplitude is small, <sup>approximations</sup>

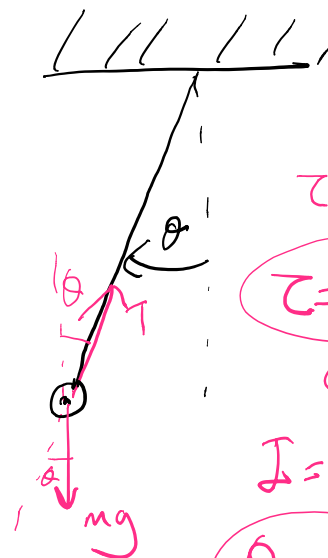
Ex



$$\tau = I \alpha$$

$$lmg \sin \theta = -ml^2 \frac{d^2 \theta}{dt^2}$$

$$\theta(t) = ?$$



$$\tau = \vec{r} \times \vec{F}$$

$$\tau = lmg \sin \theta$$

c.c.w.

$$I = ml^2$$

$$\theta \text{ c.c.w.}$$

$$lmg \sin \theta = -m l \frac{d^2 \theta}{dt^2}$$

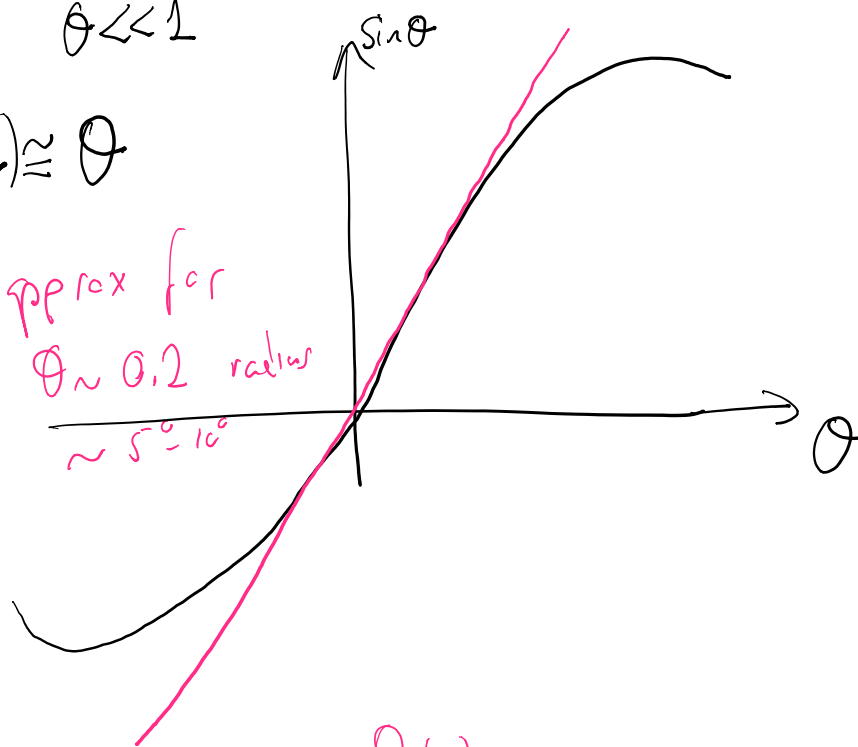
$\theta$  c.w

$$\frac{d^2 \theta}{dt^2} = -\frac{g}{l} \sin(\theta)$$

$$\theta \ll 1$$

$$\sin(\theta) \approx \theta$$

good approx for  
 $\theta \sim 0.2$  radians  
 $\sim 5^\circ - 10^\circ$



$$\frac{d^2 \theta(t)}{dt^2} = -\frac{g}{l} \sin \theta(t) \quad \text{approximation}$$

$$\frac{d^2 \theta}{dt^2} = -\frac{g}{l} \theta(t)$$

$$\theta(t) = C_1 \sin(\omega t) + C_2 \cos(\omega t)$$

$$\frac{d^2 \theta}{dt^2}(t) = -\omega^2 C_1 \sin(\omega t) - \omega^2 C_2 \cos(\omega t) = -\omega^2 \theta(t)$$

$$-\omega^2 \theta(t) = -\frac{g}{l} \theta(t)$$

$$\omega = \sqrt{\frac{g}{l}} \quad \text{Frequency of "small" oscillations}$$

$$T = \frac{2\pi}{\sqrt{\frac{g}{l}}} = 2\pi \sqrt{\frac{l}{g}}$$

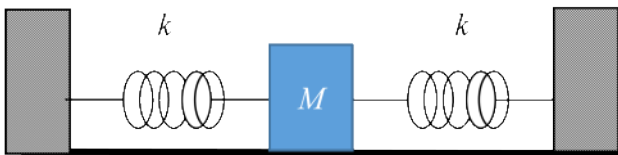
$$\theta(t=0) = \theta_0 = c_2$$

$$\frac{d\theta}{dt}(t=0) = 0 = -\omega c_1 \Rightarrow c_1 = 0$$

$$\theta(t) = \theta_0 \cos(\omega t) \quad \omega = \sqrt{\frac{g}{l}}$$

Phys 101- Instructor: M. Özgür Oktel – 2016 QUIZ-25

A mass **M** on a frictionless table is connected to two walls with two identical springs of spring constant **k**. The springs are at their relaxed length in equilibrium. Find the (angular) frequency of small oscillations of the mass.



$$|F_1| = kx$$

$$|F_2| = kx$$



$$m a = m \frac{d^2 x}{dt^2} = -|F_1| - |F_2| = -2kx$$

$$m \frac{d^2 x}{dt^2} = -2kx$$

$$\frac{d^2 x}{dt^2} + \frac{2k}{m} x = 0$$

$$\frac{d^2x}{dt^2} = -\frac{2k}{m}x$$

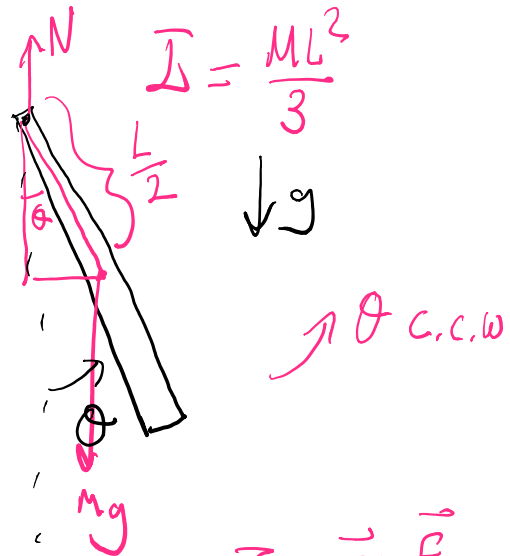
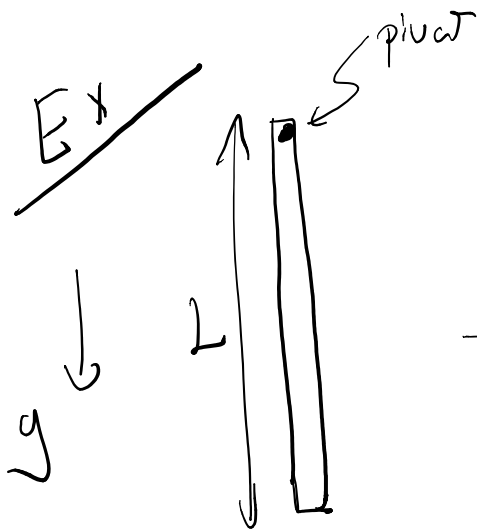
$\omega = ?$

$$x = C_1 \cos(\omega t) + C_2 \sin(\omega t)$$

$$\frac{d^2x}{dt^2} = -\omega^2 (C_1 \cos(\omega t) + C_2 \sin(\omega t))$$

$$\omega^2 = \frac{2k}{m} \Rightarrow$$

$$\omega = \sqrt{\frac{2k}{m}}$$



$\omega = ?$   
Small oscillations

$$\tau = I \alpha$$

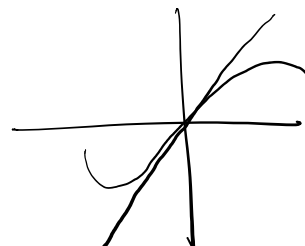
$$-\frac{MgL}{2} \sin \theta = \frac{ML^2}{3} \frac{d^2\theta}{dt^2}$$

$$\begin{aligned} \tau &= \vec{r} \times \vec{F} \\ &= |\vec{r}| |\vec{F}| \sin \theta \\ &= \frac{L}{2} \sin \theta Mg \end{aligned}$$

$$\tau = \frac{MgL}{2} \sin \theta \quad (\text{c.c.w})$$

$$\frac{d^2\theta}{dt^2} = -\frac{3}{2} \frac{g}{L} \sin \theta$$

Small oscillation  $\sin \theta \approx \theta$



Small oscillation  $\sin \theta \approx \theta$



$$\frac{d^2\theta}{dt^2} \approx -\frac{3}{2} \frac{g}{L} \theta$$

$$\theta(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t)$$

$$\frac{d^2\theta}{dt^2} = -\omega^2 \theta(t)$$

$$\omega^2 = \frac{3}{2} \frac{g}{L} \Rightarrow$$

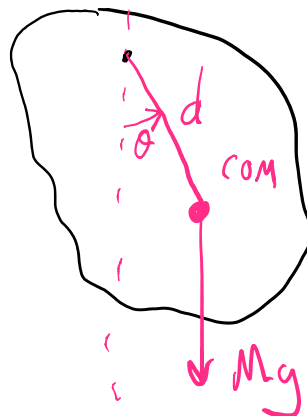
$$\omega = \sqrt{\frac{3}{2} \frac{g}{L}}$$

$$\sqrt{\frac{m/s^2}{m}} = \frac{1}{s}$$

"physical pendulum"



$I_{com}, d, M$   
 $I = I_{com} + Md^2$



$\theta \nearrow$  c.c.w.

$$\tau = \vec{r} \times \vec{F} = d M g \sin \theta$$

c.w.

$$I \alpha = \tau$$

$$(I_{com} + Md^2) \frac{d^2\theta}{dt^2} = -d M g \sin \theta$$



$$(I_{com} + Md^2) \frac{d^2\theta}{dt^2} = -$$

$$\frac{d^3\theta}{dt^2} = - \frac{dMg}{(I_{com} + Md^2)} \sin\theta$$

small oscillations  
 $\sin\theta \approx \theta$

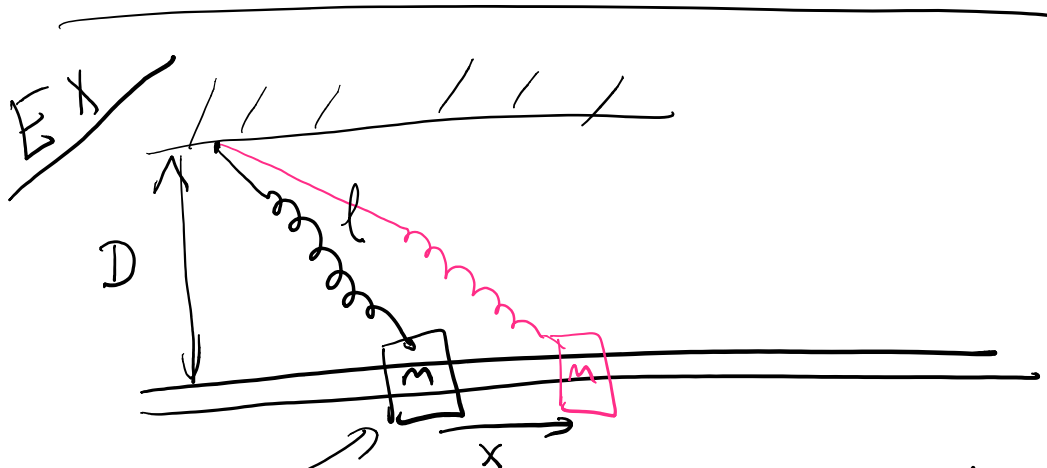
$$\frac{d^2\theta}{dt^2} = - \left( \frac{dMg}{(I_{com} + Md^2)} \right) \theta$$

$$\theta(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t)$$

$$\frac{d^2\theta}{dt^2} = -(\omega^2) \theta$$

$$\omega = \sqrt{\frac{dMg}{I_{com} + Md^2}}$$

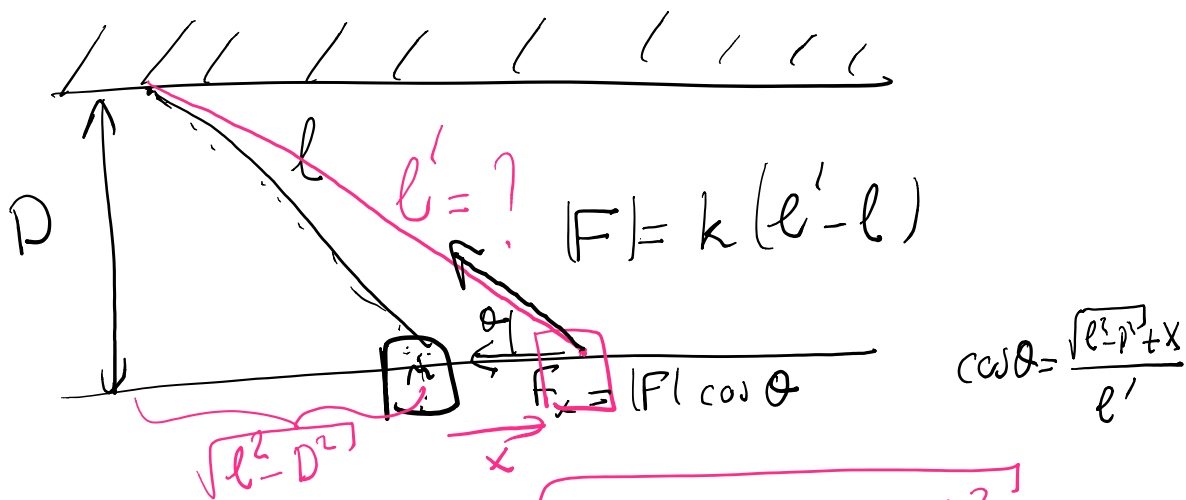
$$[\omega] = \sqrt{\frac{\cancel{kg} \cancel{m/s^2}}{\cancel{kg} \cancel{m}}} = \frac{1}{s} \checkmark$$



Based on a  
 frictionless wire

relaxed length of spring is  $l$ .

Find the frequency of small oscillations



$$l' = ? \Rightarrow l' = \sqrt{D^2 + (\sqrt{l^2 - D^2} + x)^2}$$

$$|F_x| = k(l' - l) \frac{\sqrt{l^2 - D^2} + x}{l'}$$

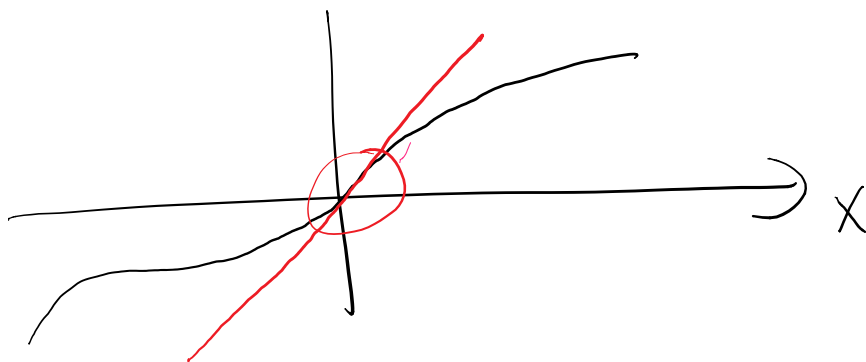
$$m \frac{d^2 x}{dt^2} = -k(l' - l) \frac{\sqrt{l^2 - D^2} + x}{l'}$$

$$m \frac{d^2 x}{dt^2} = -k \left[ \sqrt{D^2 + (\sqrt{l^2 - D^2} + x)^2} - l \right] \frac{\sqrt{l^2 - D^2} + x}{\sqrt{D^2 + (\sqrt{l^2 - D^2} + x)^2}}$$

$$= f(x)$$

$$f(x=0) = 0 \quad l' - l = 0 \quad \text{if } x = 0$$

$f(x)$  ← linear approximation!



$$f(x) \simeq f(x=0) + \left. \frac{df}{dx} \right|_{x=0} x + \dots$$

$x \ll 1$  neglect!

Taylor series

$$f(x) = f(x_0) + \left. \frac{df}{dx} \right|_{x_0} (x-x_0) + \frac{1}{2!} \left. \frac{d^2 f}{dx^2} \right|_{x_0} (x-x_0)^2 + \dots$$

$$f(x) = -k \left[ \sqrt{D^2 + (\sqrt{\ell^2 - D^2} + x)^2} - \ell \right] \frac{\sqrt{\ell^2 - D^2} + x}{\sqrt{D^2 + (\sqrt{\ell^2 - D^2} + x)^2}}$$

$$\frac{df}{dx} = -k \left[ \frac{1}{2} \frac{2(\sqrt{\ell^2 - D^2} + x)}{\sqrt{D^2 + (\sqrt{\ell^2 - D^2} + x)^2}} \right] \frac{\sqrt{\ell^2 - D^2} + x}{\sqrt{D^2 + (\sqrt{\ell^2 - D^2} + x)^2}}$$

$$-k \left[ \frac{(\sqrt{\ell^2 - D^2} + x)}{\sqrt{D^2 + (\sqrt{\ell^2 - D^2} + x)^2}} \right] \frac{1}{2} \frac{2(\sqrt{\ell^2 - D^2} + x)}{\sqrt{D^2 + (\sqrt{\ell^2 - D^2} + x)^2}}$$

$$\left. \frac{df}{dx} \right|_{x=0} = -k \left[ \frac{1}{2} \frac{2 \sqrt{l^2 - D^2}}{l} \right] \frac{\sqrt{l^2 - D^2}}{l}$$

$$= -k \left( \frac{l - l}{l} \right) \dots$$

$$= -k \frac{l^2 - D^2}{l^2}$$

Now

$$\frac{d^2 x}{dt^2} = -\frac{k}{m} \frac{l^2 - D^2}{l^2} x$$

$$x(t) = C_1 \cos(\omega t) + C_2 \sin(\omega t)$$

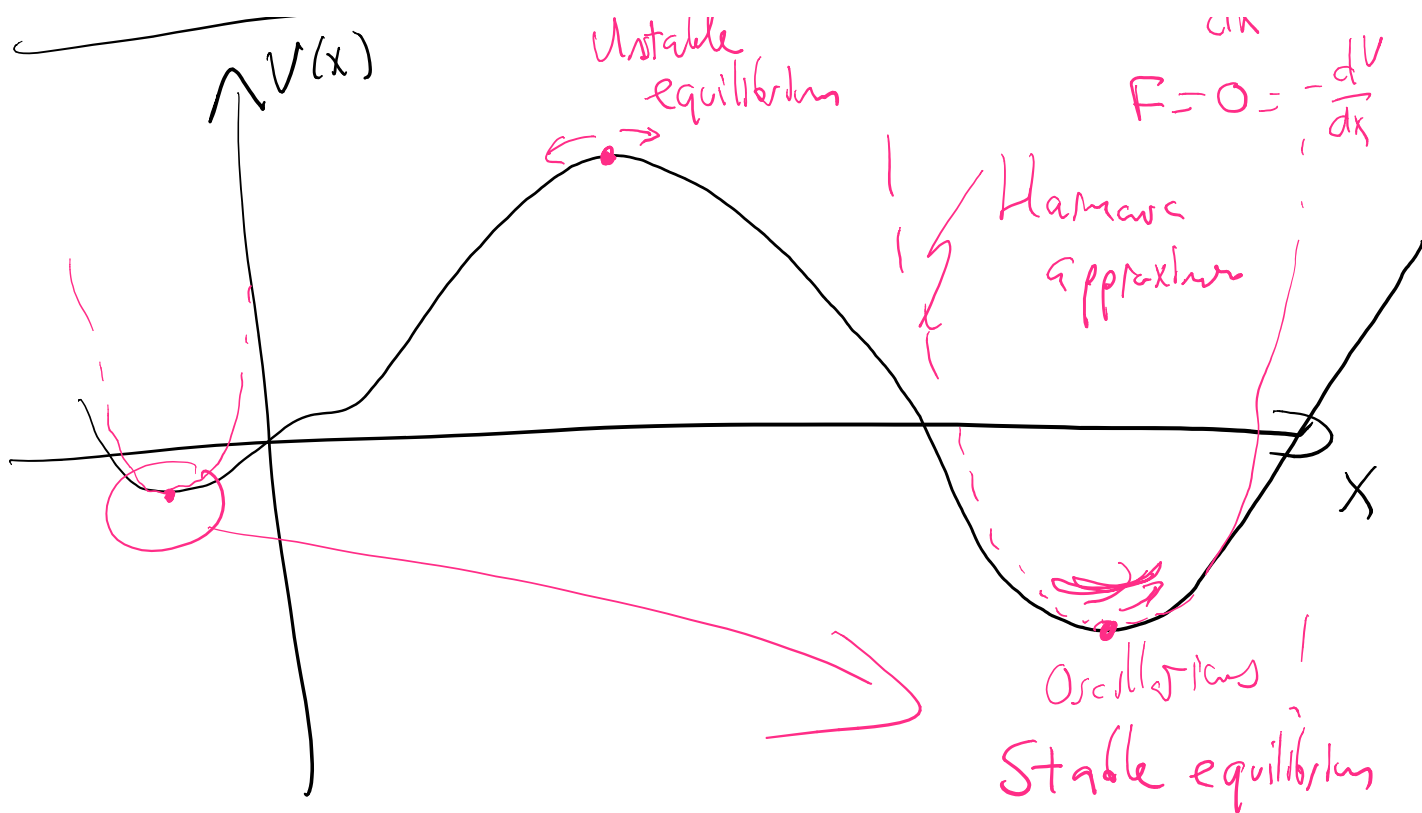
$$\omega = \sqrt{\frac{k}{m} \frac{l^2 - D^2}{l^2}}$$

Graph properties  
 $\Delta V(x)$

unstable  
equilibrium

$$F = -\frac{dV(x)}{dx}$$

$$F=0 = -\frac{dV}{dx}$$



Energy conserving  
No friction?

$\Rightarrow$  Damped oscillations.