

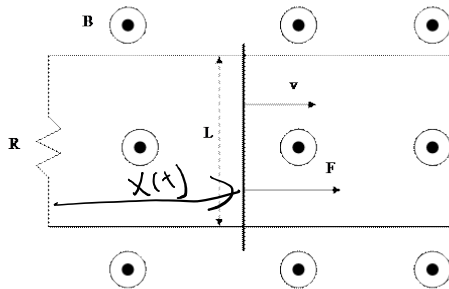
Quiz 24

PHYSICS 102- Instructor: M. Özgür OKTEL- Spring 2016

A rod of length L can slide without friction on rails as shown in the figure. The rod and rails have negligible resistance but are connected to a resistor with resistance R . If the rod is moving with velocity v as shown in the figure.

a) Find the direction and magnitude of the current on the resistor.

b) To keep the rod moving with velocity v what is the force that must be applied to it? Find F .



$$|\mathcal{E}| = \left| \frac{d\Phi}{dt} \right| = BL \frac{dx}{dt} = BLv$$

a)

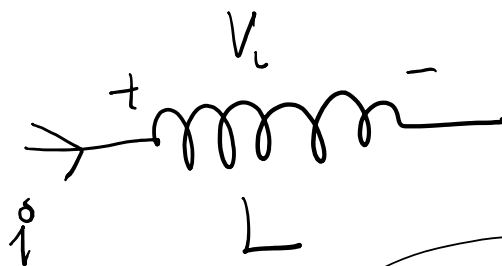
$$i = \frac{\mathcal{E}}{R} = \boxed{\frac{BLv}{R}}$$

b)

$$\vec{F} = i \vec{L} \times \vec{B} \Rightarrow i L B = |\vec{F}|$$

$$\boxed{\frac{B^2 L^2 v}{R} = |\vec{F}|}$$

Inductors



$$V_L = L \frac{di}{dt} = \frac{d}{dt}(Li) = \frac{d}{dt}(\Phi)$$

$$P = V i = L \frac{di}{dt} i = \frac{1}{2} \frac{d}{dt}(L i^2) = \frac{d}{dt} \left(\frac{1}{2} L i^2 \right)$$

$$\frac{d}{dt}(i^2) = 2 i \frac{di}{dt}$$

$$\frac{d}{dt}(\dot{i}^2) = 2 \dot{i} \frac{d\dot{i}}{dt}$$

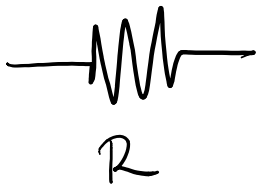
$$U_L = \frac{1}{2} L \dot{i}^2$$

potential energy stored in an inductor

$$\left[U_C = \frac{1}{2} C V^2 \quad U_E = \frac{1}{2} \epsilon_0 E^2 \right]$$

energy density

$$U_B = \frac{1}{2 \mu_0} B^2 \Rightarrow \text{energy density of the magnetic field.}$$



$$V = R \dot{i}$$

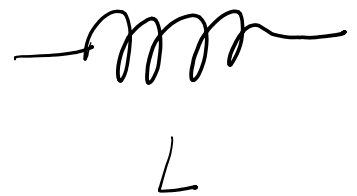
Dissipate



$$\dot{i} = C \frac{dV}{dt}$$

Store energy

$$U_C = \frac{1}{2} C V^2$$

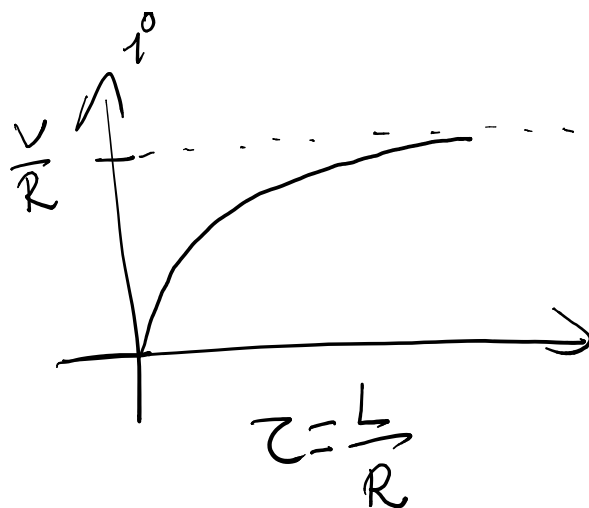
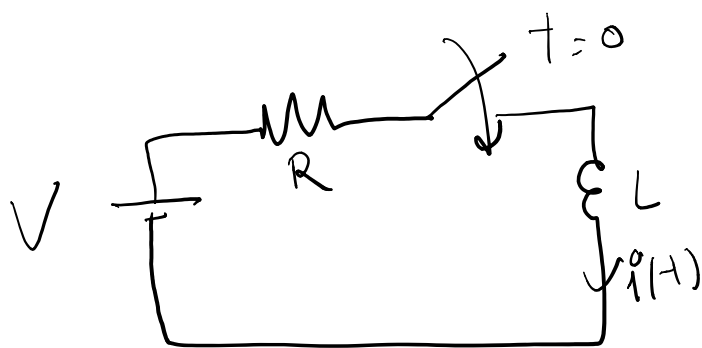


$$V = L \frac{d\dot{i}}{dt}$$

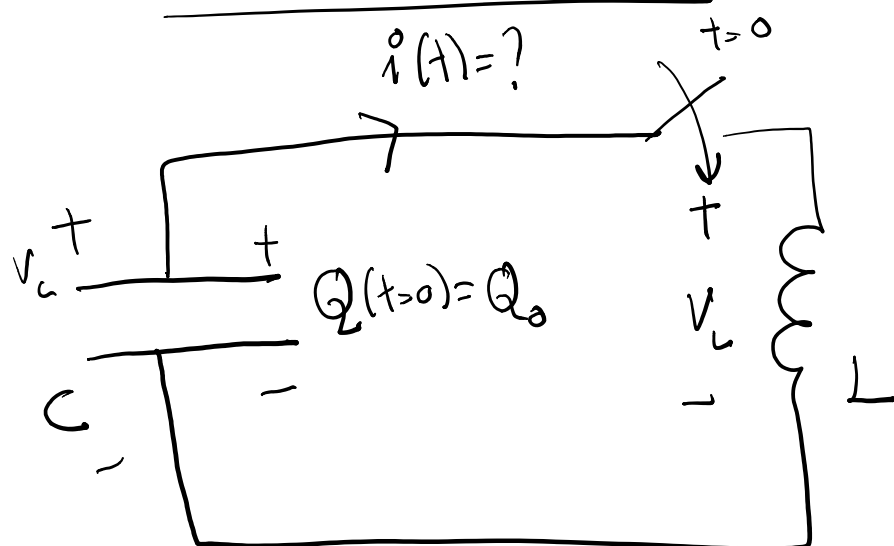
Store energy

$$U_L = \frac{1}{2} L \dot{i}^2$$

Recall we solved RL



LC circuit



Initial energy
 $E_i = \frac{1}{2} \frac{Q_0^2}{C}$
 will be conserved.

$$V_L = L \frac{di}{dt} \Rightarrow V_C = \frac{Q(t)}{C}$$

$$i(t) = -\frac{dQ}{dt}$$

$$L \frac{di}{dt} = \frac{Q(t)}{C}$$

$$i = -\frac{dQ}{dt} \Rightarrow \frac{d}{dt} \left(-\frac{dQ}{dt} \right)$$

$$\overset{d+}{\curvearrowright} \quad C \quad \frac{di^0}{dt} = - \overset{\sigma^+}{\frac{d^2}{dt^2}} Q \quad \downarrow \frac{v}{dt}$$

$$-L \frac{d^2 Q}{dt^2} = \frac{Q}{C}$$

$$\boxed{\frac{d^2}{dt^2} (Q(t)) = -\frac{1}{LC} Q(t)}$$

Only 2 functions can satisfy this $\cos(\Omega t), \sin(\Omega t)$

$$Q(t) = A \cos(\Omega t) + B \sin(\Omega t)$$

$$\frac{dQ}{dt} = -\Omega A \sin(\Omega t) + \Omega B \cos(\Omega t)$$

$$\frac{d^2 Q}{dt^2} = -\Omega^2 A \cos(\Omega t) - \Omega^2 B \sin(\Omega t)$$

$$\frac{d^2 Q}{dt^2} = -\Omega^2 Q(t) \Leftrightarrow \frac{d^2 Q}{dt^2} = -\frac{1}{LC} Q(t)$$

$$\Omega^2 = \frac{1}{LC}$$

$$\Omega = \frac{1}{\sqrt{LC}}$$

$$\omega_0$$

$$Q(t) = A \cos\left(\frac{t}{\sqrt{LC}}\right) + B \sin\left(\frac{t}{\sqrt{LC}}\right)$$

$$Q(t=0) = Q_0 = A \Rightarrow A = Q_0$$

$$i(t) = -\frac{dQ}{dt} = -\frac{1}{\sqrt{LC}} A \sin\left(\frac{t}{\sqrt{LC}}\right) + \frac{B}{\sqrt{LC}} \cos\left(\frac{t}{\sqrt{LC}}\right)$$

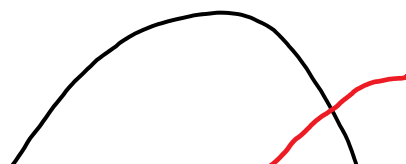
$$i(t=0) = 0 = \frac{B}{\sqrt{LC}} \Rightarrow B = 0$$

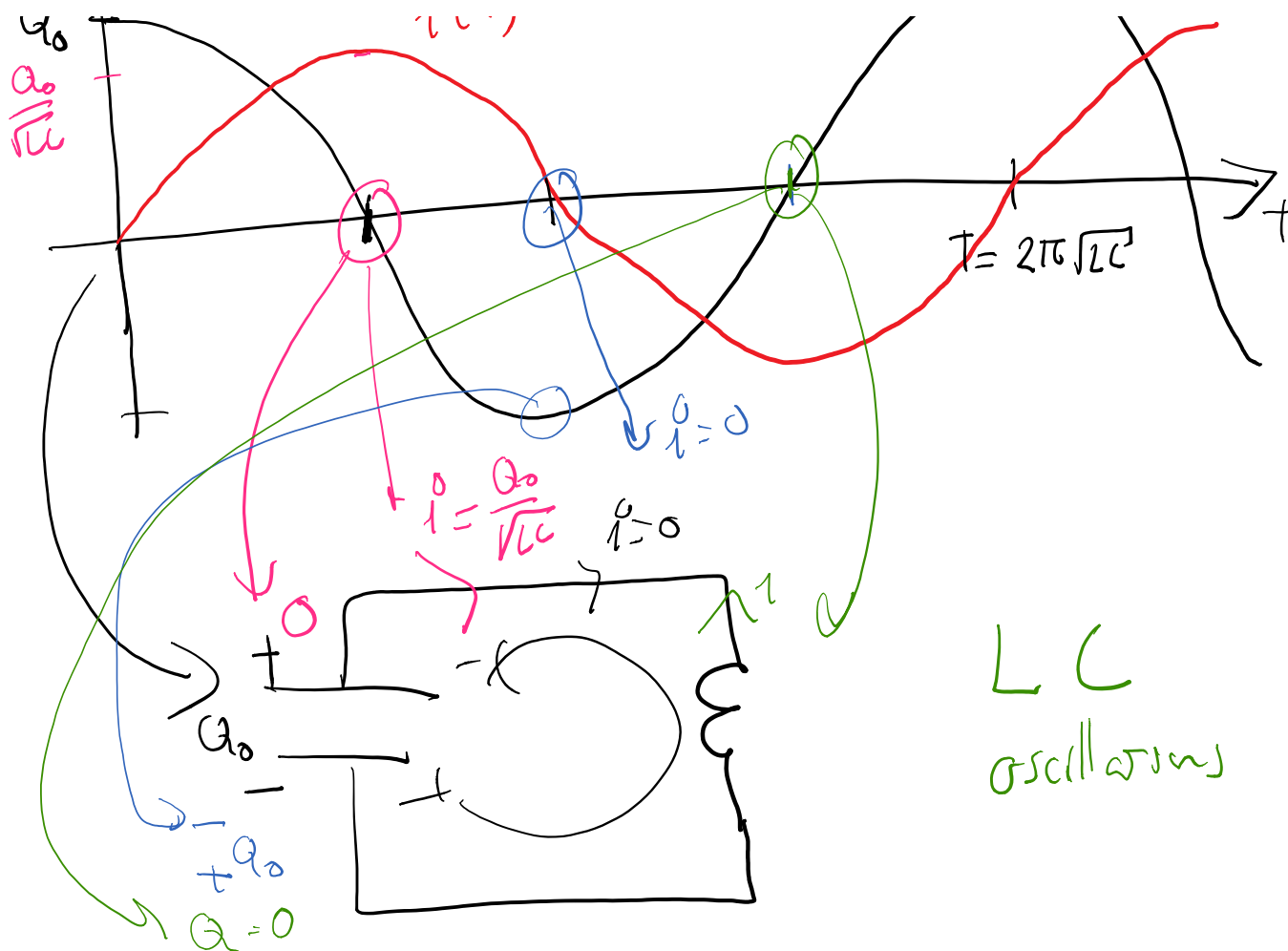
$$Q(t) = Q_0 \cos\left(\frac{t}{\sqrt{LC}}\right)$$

$$i(t) = -\frac{dQ}{dt} = \frac{Q_0}{\sqrt{LC}} \sin\left(\frac{t}{\sqrt{LC}}\right)$$

$$\Omega = \frac{1}{\sqrt{LC}}$$

$$T = \frac{2\pi}{\Omega}$$





LC
oscillations

$$Q(t) = Q_0 \cos\left(\frac{t}{\sqrt{LC}}\right)$$

$$i(t) = \frac{Q_0}{\sqrt{LC}} \sin\left(\frac{t}{\sqrt{LC}}\right)$$

$$U_C = \frac{1}{2} \frac{Q(t)^2}{C}$$

$$= \frac{1}{2} \frac{1}{C} Q_0^2 \cos^2\left(\frac{t}{\sqrt{LC}}\right)$$

$$U_L = \frac{1}{2} L i(t)^2$$

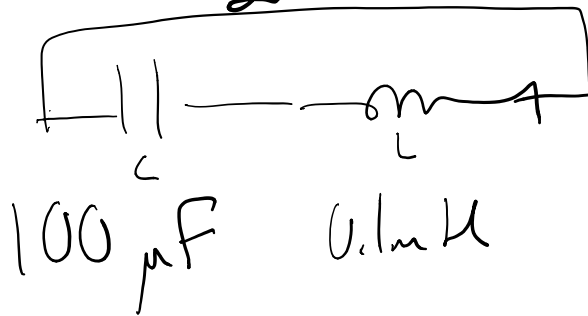
$$= \frac{1}{2} L \frac{Q_0^2}{LC} \sin^2\left(\frac{t}{\sqrt{LC}}\right)$$

$$U_C + U_L = \frac{1}{2} \frac{Q_0^2}{C} \left(\cos^2\left(\frac{t}{\sqrt{LC}}\right) + \sin^2\left(\frac{t}{\sqrt{LC}}\right) \right)$$

$$U_C + U_L = \frac{1}{2} C (\cos^2 \omega t + \sin^2 \omega t)$$

$$= \frac{1}{2} \frac{Q_0^2}{C}$$

(1)

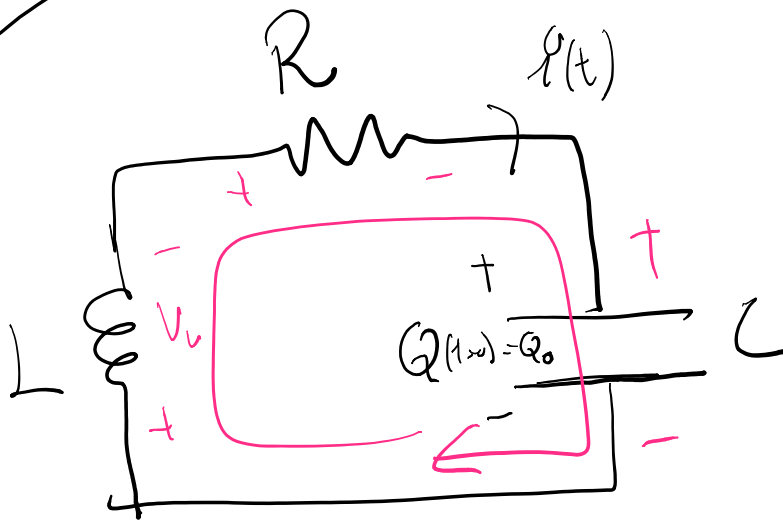


$$T = 2\pi \sqrt{LC}$$

$$= 2\pi \sqrt{10^{-4} 10^{-4}} = 2\pi 10^{-4} \text{ sec}$$

$$\sim 1 \text{ msc}$$

$E \times$



$$i(t) = \frac{dQ}{dt}$$

RLC circuit.

$$V_L = L \frac{di}{dt}$$

$$V_R = Ri$$

$$V_C = \frac{Q(t)}{C}$$

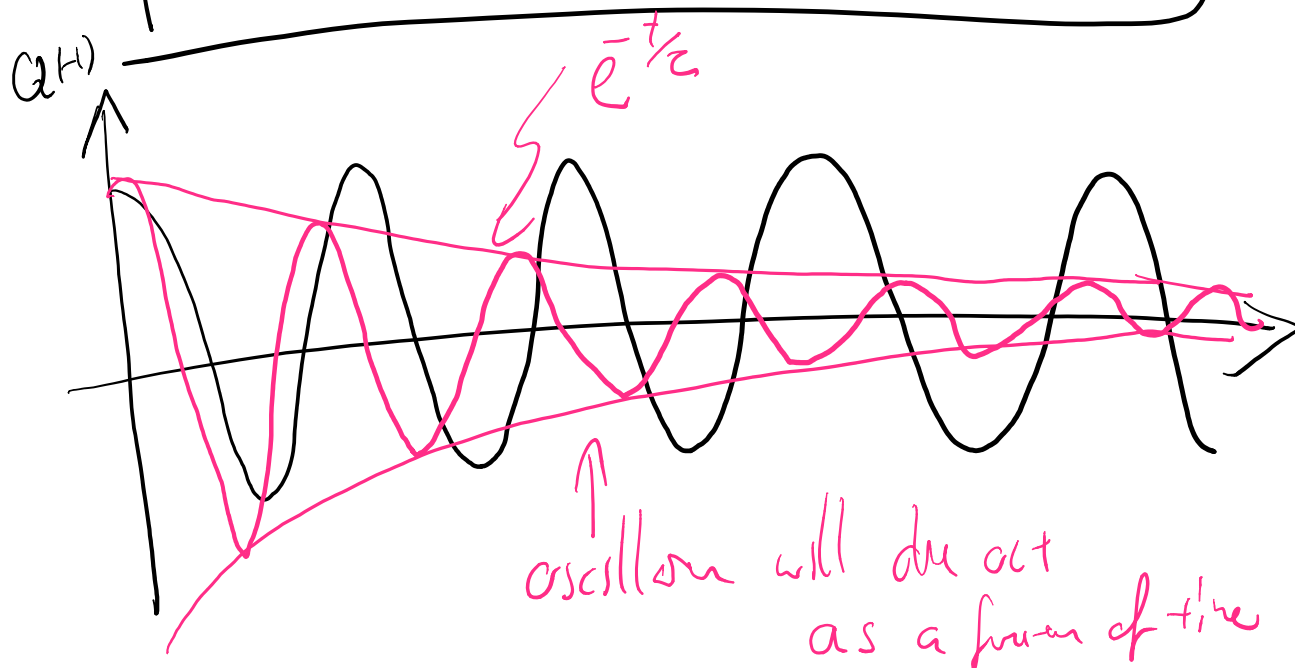
$$V_L + V_R + V_C = 0$$

$$i = \frac{dQ}{dt}$$

$$i = \frac{dq}{dt}$$

$$L \frac{di}{dt} + Ri + \frac{Q}{C} = 0$$

$$\frac{d^2}{dt^2} Q + \frac{R}{L} \frac{dQ}{dt} + \frac{Q}{LC} = 0$$

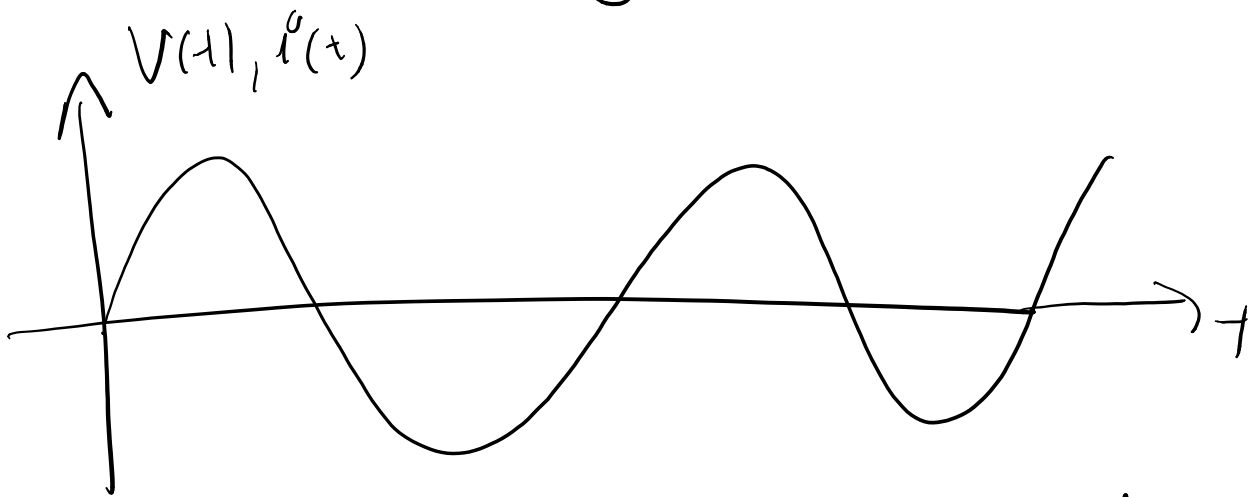


$$Q(t) = Q_0 \cos(\Omega t) e^{-t/\tau}$$

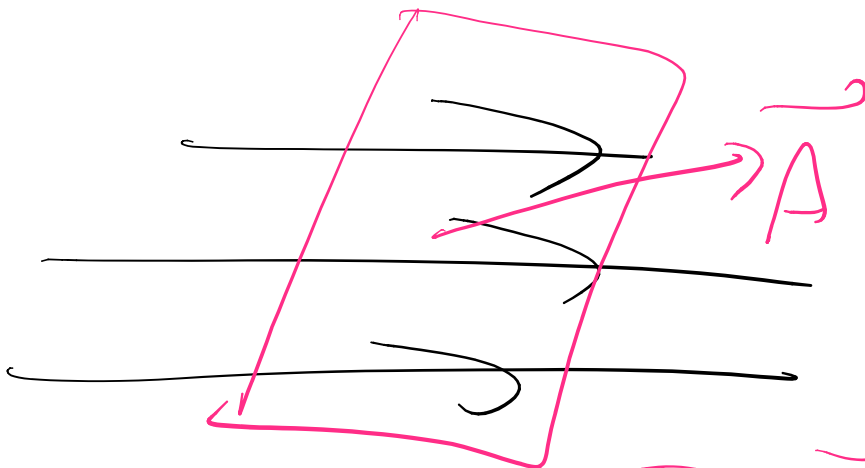
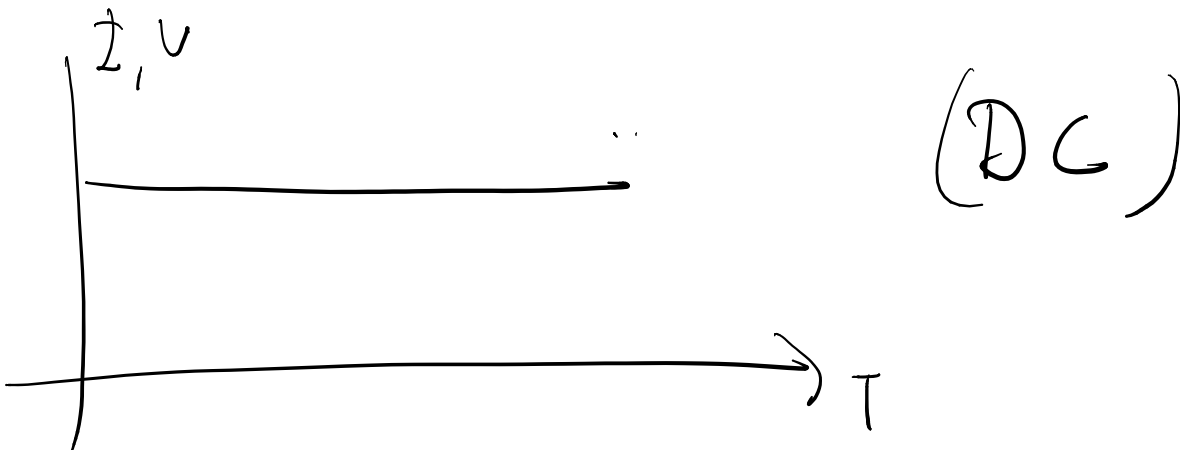
$$\Omega \neq \frac{1}{\sqrt{LC}} = \Omega_0$$

$$\tau = \frac{L}{R}$$

Alternating Current (AC)



Most of our power systems rely on AC



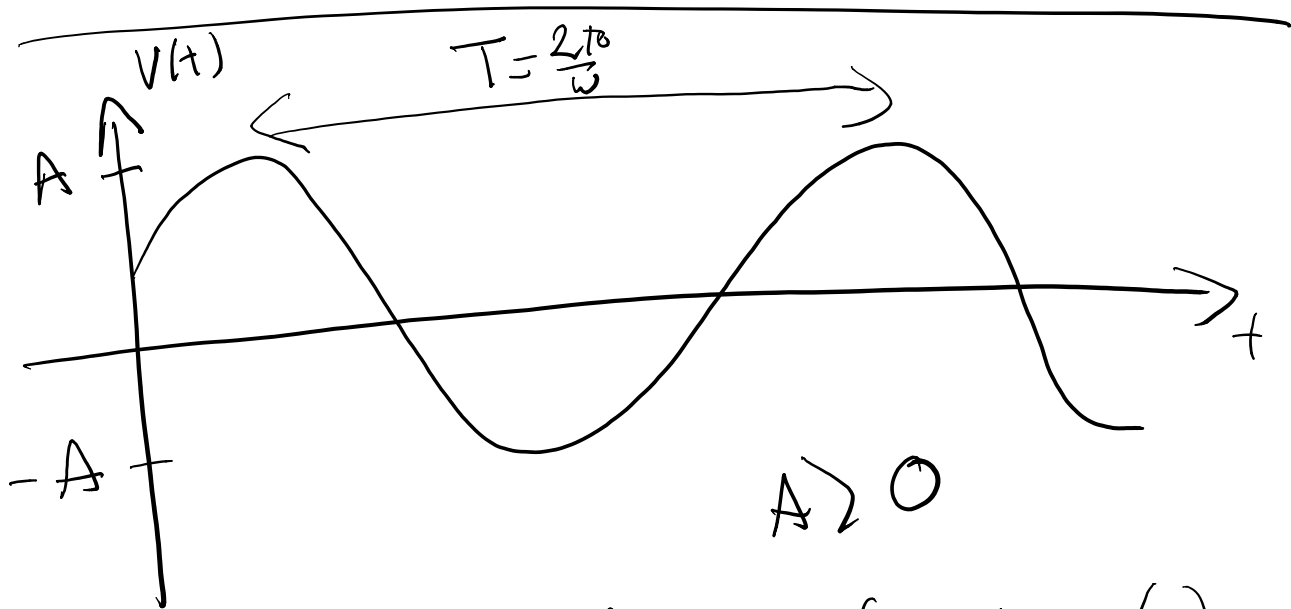
$$\Phi = \vec{B} \cdot \vec{A} = |\vec{B}| |\vec{A}| \cos \theta$$

1st

$$\frac{d\phi}{dt} = -\omega |\vec{B}| |\vec{A}| \sin(\omega t)$$

$$\mathcal{P} = |\vec{B}| |\vec{A}| \cos \theta$$

ωt



$$V(t) = A \cos(\omega t + \phi)$$

Amplitude

Ang. Frequency

$$\nu = \frac{\omega}{2\pi}$$

$$T = \frac{1}{\nu} = \frac{2\pi}{\omega}$$

phase

$$-\pi < \phi < \pi$$

$$\sin(\theta) = \cos(\theta - \frac{\pi}{2})$$

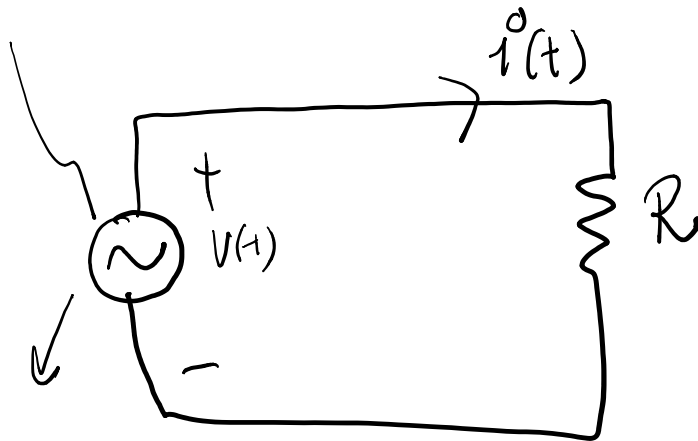
$$5 \sin(\omega t) = 5 \cos(\omega t - \frac{\pi}{2})$$

$$A = 5$$

$$\omega = \omega$$

$$\phi = -\frac{\pi}{2}$$

For AC circuits Phase angle as well as
AC voltage same Amplitude are important.

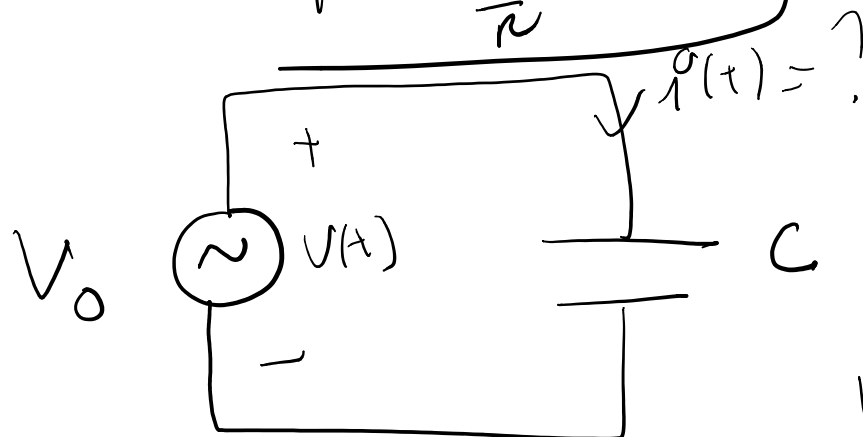


$$i(t) = \frac{V(t)}{R}$$

$$V(t) = V_0 \cos(\omega t)$$

$$i(t) = \frac{V_0}{R} \cos(\omega t)$$

$$Z = \frac{V_0}{\frac{V_0}{R}} = R$$



$$i = C \frac{dV}{dt}$$

$$V(t) = V_0 \cos(\omega t)$$

$$i(t) = C \frac{d}{dt} (V_0 \cos(\omega t))$$

$$= -C V_0 \omega \sin(\omega t)$$

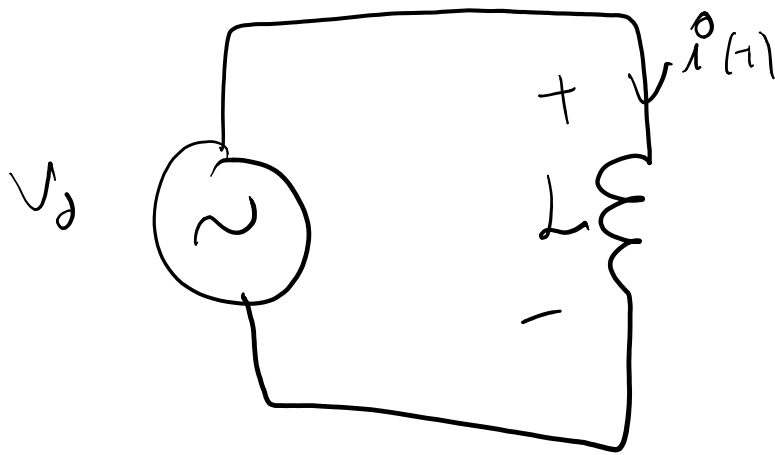
$$= -C V_0 \omega \cos(\omega t - \frac{\pi}{2})$$

$$\begin{aligned} i(t) &= C V_0 \omega \cos(\omega t + \frac{\pi}{2}) \\ &= \underbrace{(C\omega)} V_0 \cos(\omega t + \frac{\pi}{2}) \end{aligned}$$

Across the capacitor $i(t)$ leads $V(t)$
by $\pi/2$

$$\frac{|V|}{|i|} \sim \frac{V_0}{C\omega V_0} = \boxed{\frac{1}{\omega C}} = Z$$

AC circuit $\frac{V_{\text{amp}}}{I_{\text{amp}}} = Z$ \swarrow impedance



$$V(t) = V_0 \cos(\omega t)$$

$$i(t) = ?$$

$$V(t) = L \frac{di^0}{dt}$$

$$V_0 \cos(\omega t) = L \frac{d}{dt} i^0(t)$$

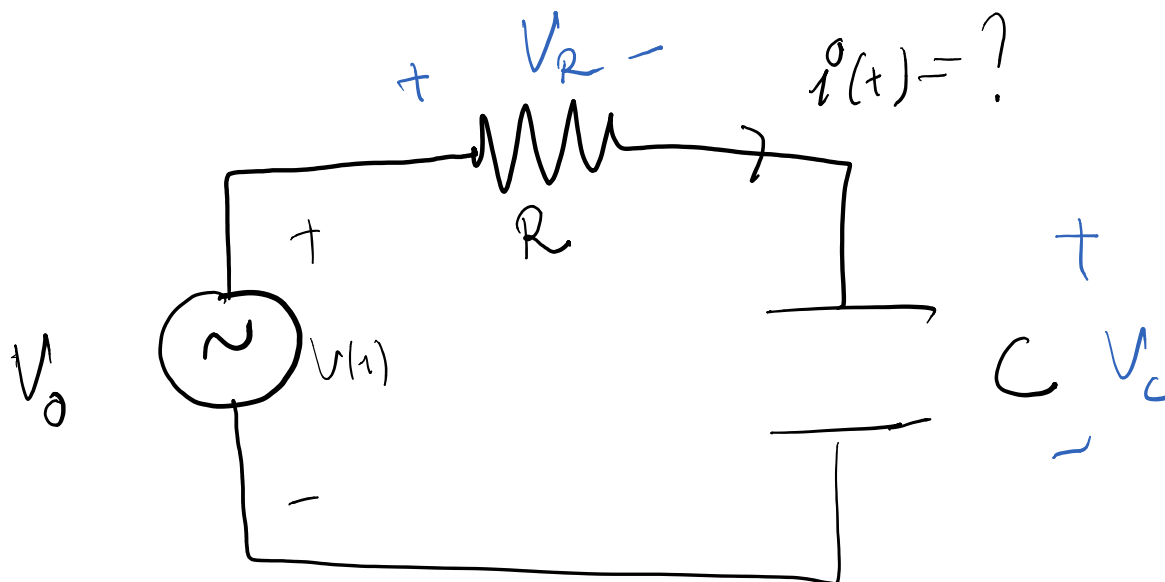
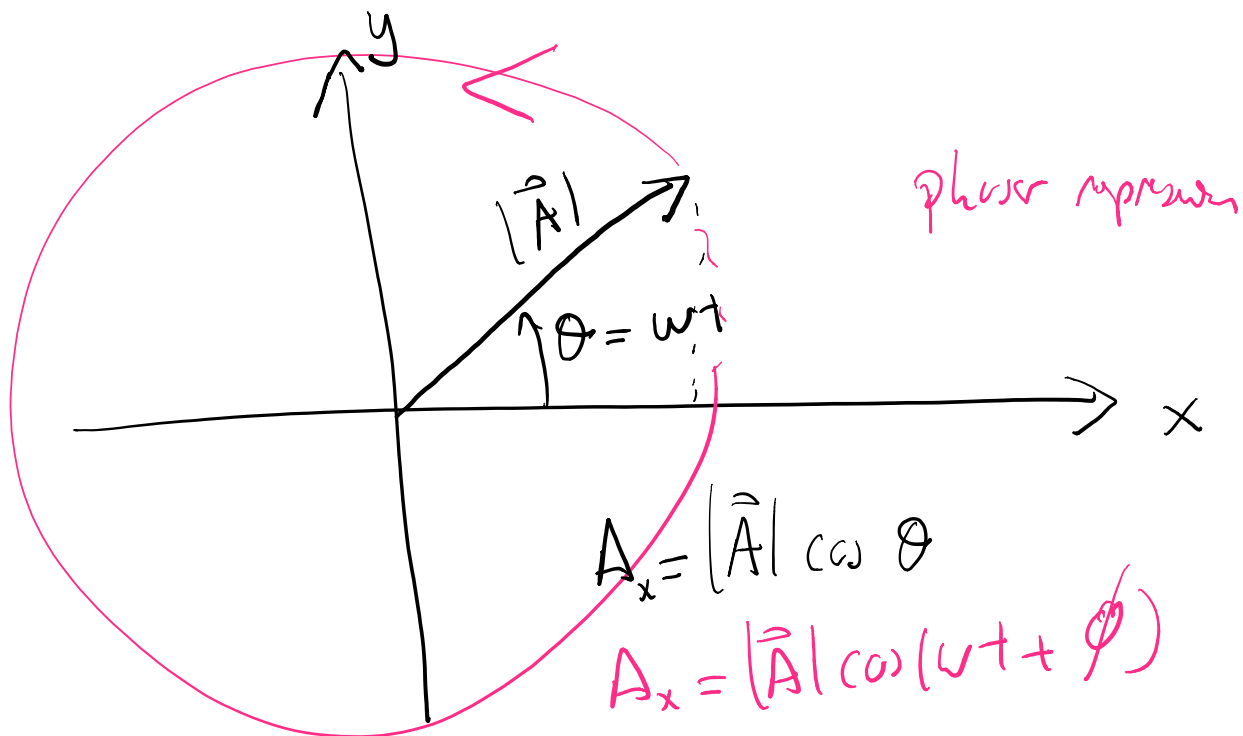
$$i^0(t) = \frac{V_0}{L\omega} \sin(\omega t)$$

$$\frac{di^0}{dt} = \frac{V_0}{L\omega} \cos(\omega t) \Rightarrow L \frac{di^0}{dt} = V_0 \cos(\omega t) \checkmark$$

$$i^0(t) = \frac{V_0}{L\omega} \cos(\omega t - \frac{\pi}{2})$$

$$\frac{V_{\text{max}}}{i_{\text{max}}^0} = \frac{V_0}{\frac{V_0}{L\omega}} = L\omega$$

Current across an inductor lags behind the voltage by $\frac{\pi}{2}$



$$V(t) = V_0 \cos(\omega t) \quad i(t) = ?$$

$$V_R(t) = R i(t)$$

$$V_C(t) = ?$$

$$C \frac{dV_C}{dt} = i(t)$$

Capacitor $|Z| = \frac{1}{\omega C}$ $i(t)$ leads $v(t)$ by $\frac{\pi}{2}$

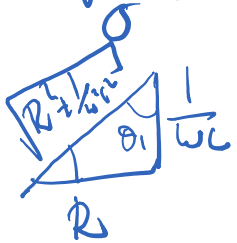
if $i(t) = i_0 \cos(\omega t + \phi_i)$

$$V_C(t) = \frac{i_0}{\omega C} \cos(\omega t + \phi_i - \frac{\pi}{2})$$

$$V_R(t) = R i_0 \cos(\omega t + \phi_i)$$

$$V_0 \cos(\omega t) = V_R + V_C$$

$$V_0 \cos(\omega t) = i_0 R \cos(\omega t + \phi_i) + \frac{i_0}{\omega C} \sin(\omega t + \phi_i)$$



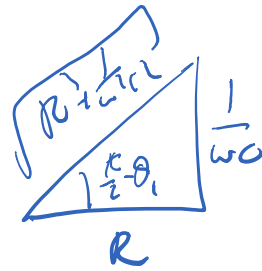
$$\cos \theta_1 \sin \theta_2 + \cos \theta_2 \sin \theta_1 = \sin(\theta_1 + \theta_2)$$

$$= i_0 \sqrt{R^2 + \frac{1}{\omega^2 C^2}} \left[\sin \theta_1 \cos(\omega t + \phi_i) + \cos \theta_1 \sin(\omega t + \phi_i) \right]$$

$$V_0 \cos(\omega t) = i_0 \sqrt{R^2 + \frac{1}{\omega^2 C^2}} \sin(\omega t + \phi_i - \theta_1)$$

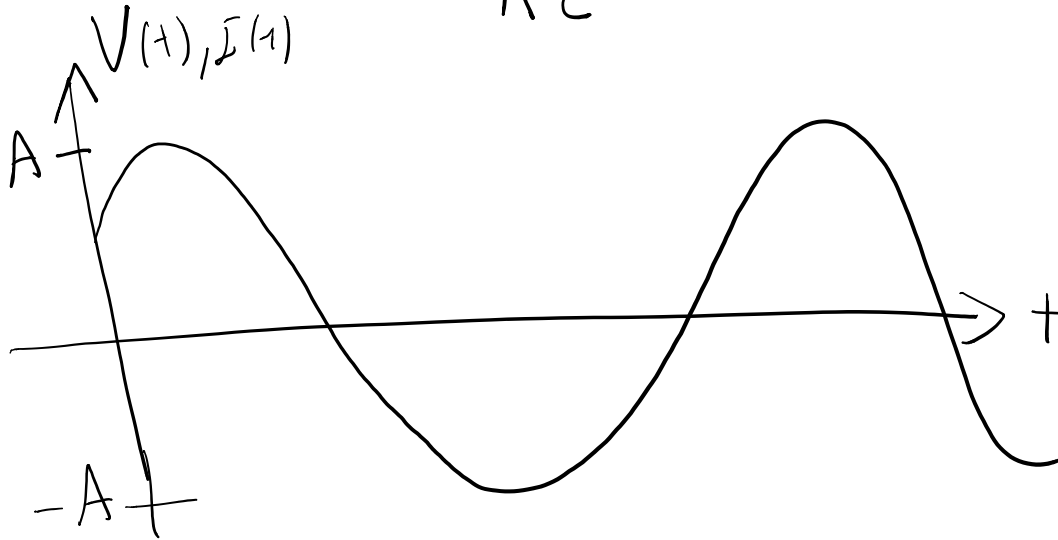
$$\cos(\omega t + \phi_i - \theta_1 - \frac{\pi}{2})$$

$$i_0 = \frac{V_0}{\sqrt{R^2 + \frac{1}{\omega^2 C^2}}}$$



$$\phi_i = \arctan \frac{1}{\omega C R}$$

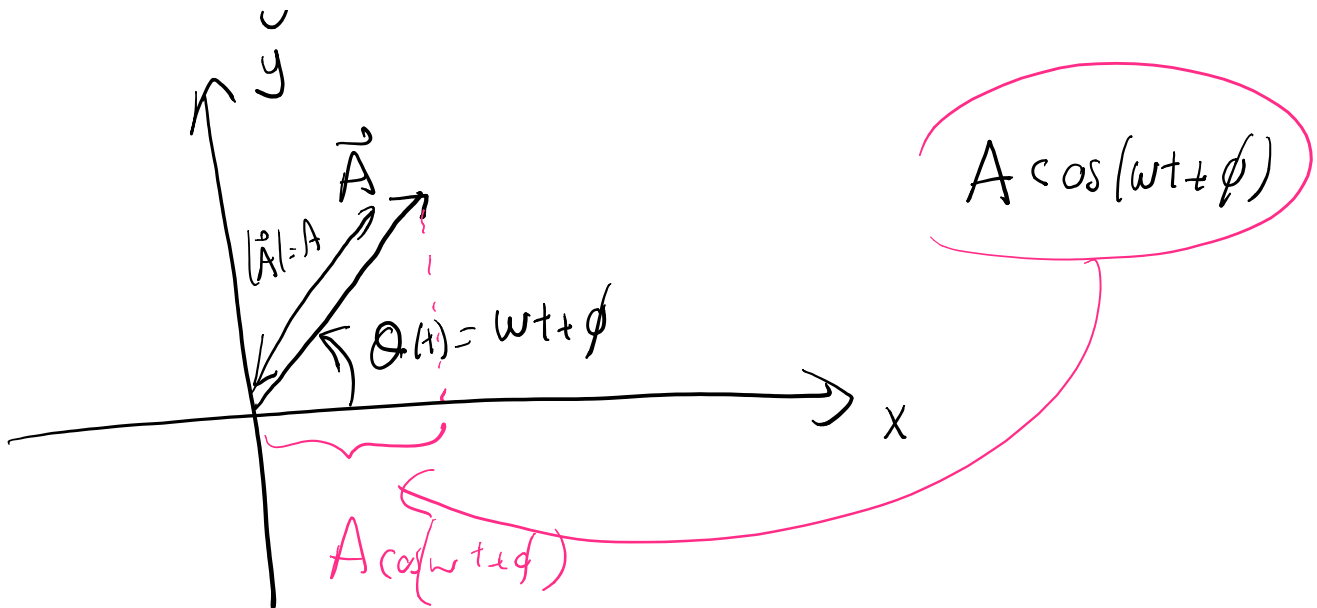
AC



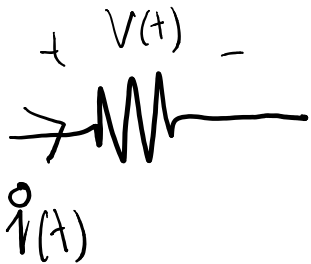
$$V(t) = A \cos(\omega t + \phi)$$

Amplitude
angular freq
 $\omega = \frac{2\pi}{T}$
phase

$\omega \rightarrow$ will be the same for all currents
and voltages
in y



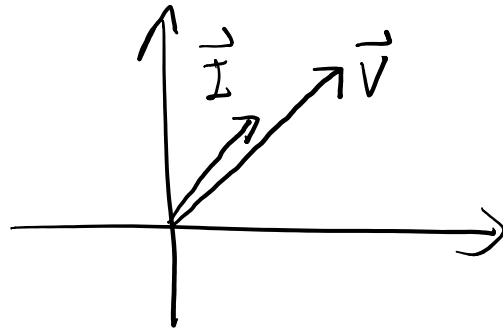
Resistor



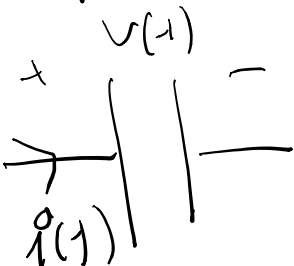
$$V(t) = V_0 \cos(\omega t) \quad \boxed{\text{memorizer}}$$

$$i(t) = \frac{V(t)}{R} = \frac{V_0}{R} \cos(\omega t)$$

$$Z = \frac{|\vec{V}|}{|\vec{I}|} = R$$



Capacitor

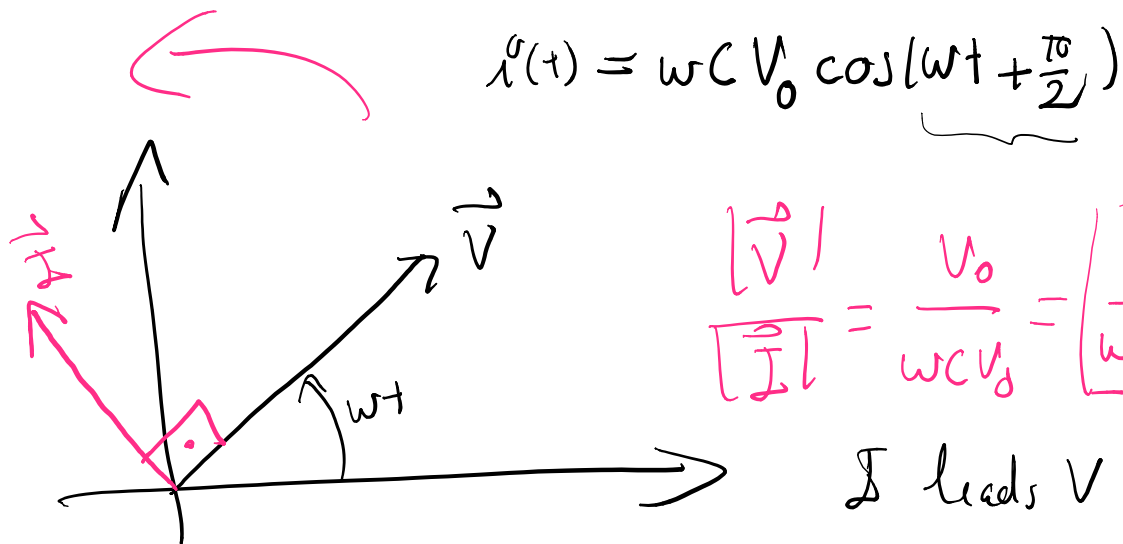


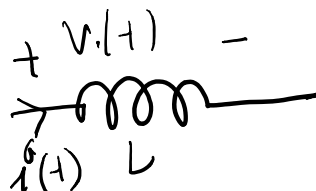
$$V(t) = V_0 \cos(\omega t)$$

$$i(t) = C \frac{dV(t)}{dt} = -C V_0 \omega \sin(\omega t)$$

$$i(t) = -\omega C V_0 \cos\left(\omega t - \frac{\pi}{2}\right)$$

$$i(t) = \omega C V_0 \cos\left(\omega t + \frac{\pi}{2}\right)$$



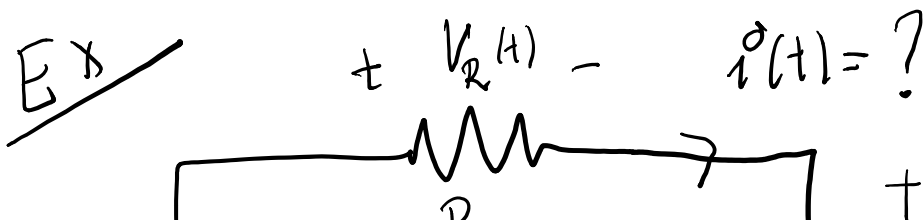
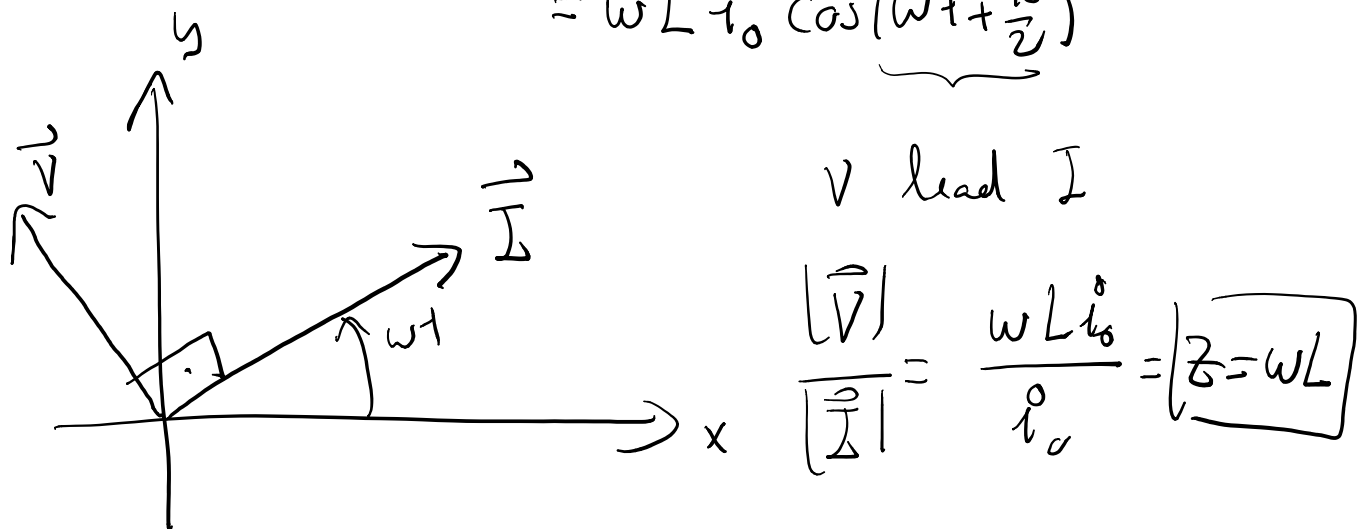


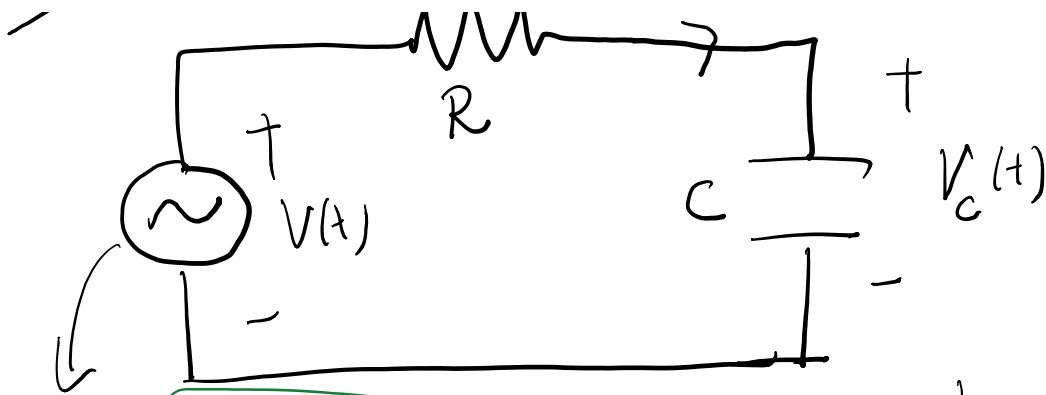
$$i(t) = i_0 \cos(\omega t)$$

$$V(t) = L \frac{di}{dt}$$

$$V(t) = -\omega L i_0 \sin(\omega t)$$

$$= \omega L i_0 \cos(\omega t + \frac{\pi}{2})$$





$$V(t) = V_0 \cos(\omega t)$$

Find the average power dissipated in the resistor.

$$V(t) = V_R(t) + V_C(t)$$

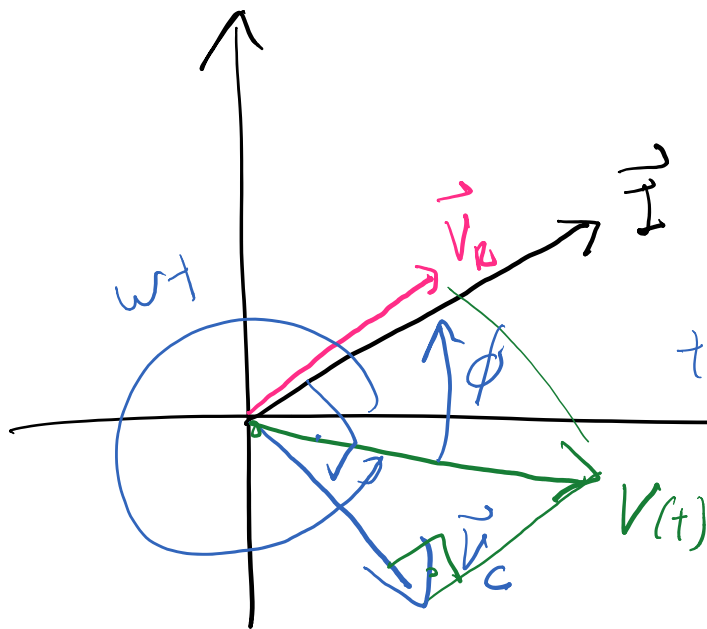
$$\vec{V}_R = R \vec{I}$$

$$|\vec{V}_R| = R i^0$$

$$\vec{V}_C = ?$$

$$\tan \phi = \frac{V_C}{V_R} = \frac{\frac{1}{\omega C} i^0}{R i^0} = \boxed{\frac{1}{\omega C R}}$$

$$|\vec{V}_C| = \frac{1}{\omega C} i^0$$



$$\vec{V}(t) = \vec{V}_C + \vec{V}_R$$

$$|V(t)| = \sqrt{V_C^2 + V_R^2}$$

$$= \sqrt{R^2 i^0^2 + \frac{1}{\omega^2 C^2} i^0^2} = \sqrt{R^2 + \frac{1}{\omega^2 C^2}} i^0$$

$$i_0 = \frac{V_0}{\sqrt{R^2 + \frac{1}{\omega^2 C^2}}}$$

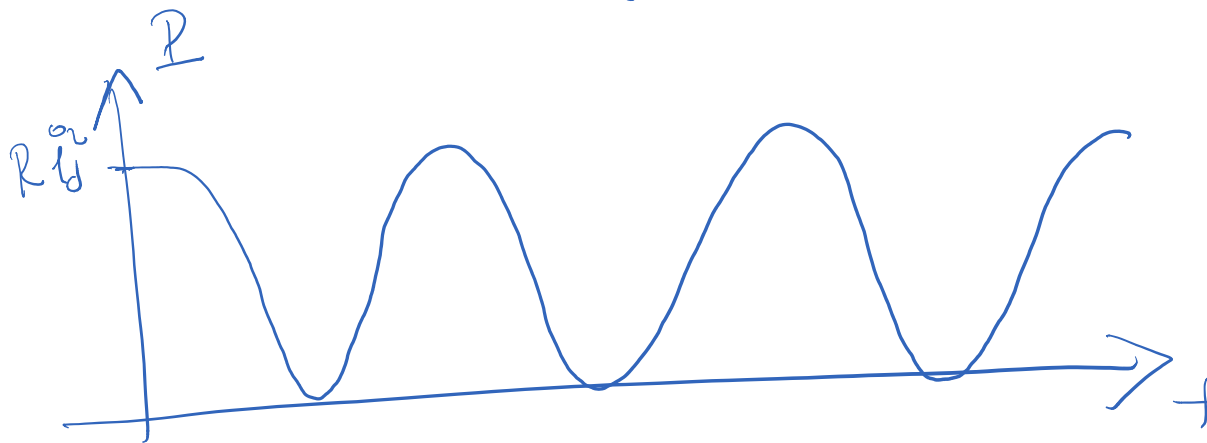
$$i(t) = \frac{V_0}{\sqrt{R^2 + \frac{1}{\omega^2 C^2}}} \cos(\omega t + \phi)$$

$$\phi = \arctan\left(\frac{1}{\omega RC}\right)$$

$$P(t) = V_R(t) i(t)$$

$$= R i^2(t)$$

$$= R i_0^2 \cos^2(\omega t + \phi)$$



$$P_{avg} = \frac{1}{T} \int_0^T P(t) dt$$

$$= \frac{1}{T} \int_0^T R i_0^2 \cos^2(\omega t + \phi) dt$$

$$= \frac{1}{T} \int_0^T R i_0^2 \cos^2(\omega t + \phi) dt$$

$$\cos^2 \theta = \frac{1}{2} (\cos 2\theta + 1)$$

$$= \frac{R i_0^2}{T} \frac{1}{2} \int_0^T (\cos(2\omega t + 2\phi) + 1) dt$$

$$= \frac{R i_0^2}{2} \left[\frac{1}{T} \left(\frac{1}{2\omega} \sin(2\omega t + 2\phi) \right) \Big|_0^T + \frac{1}{T} t \Big|_0^T \right]$$

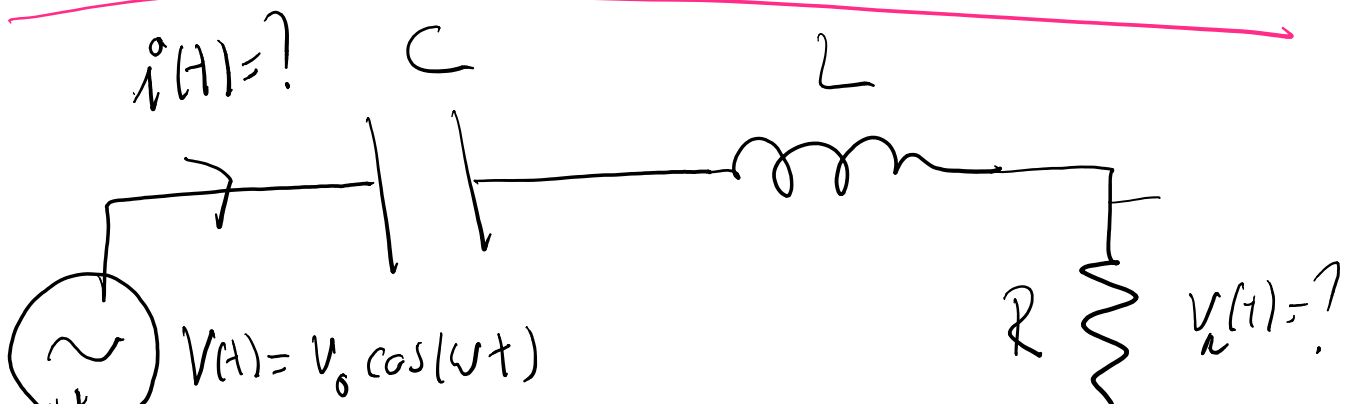
$$T = \frac{2\pi}{\omega} \quad \frac{1}{4\pi} \left[\underbrace{\sin(2\omega \frac{2\pi}{\omega} + 2\phi)}_{\sin 4\pi} - \cancel{\sin(2\phi)} \right]$$

$$P_{avg} = R \frac{i_0^2}{2}$$

$$= R i_{RMS}^2$$

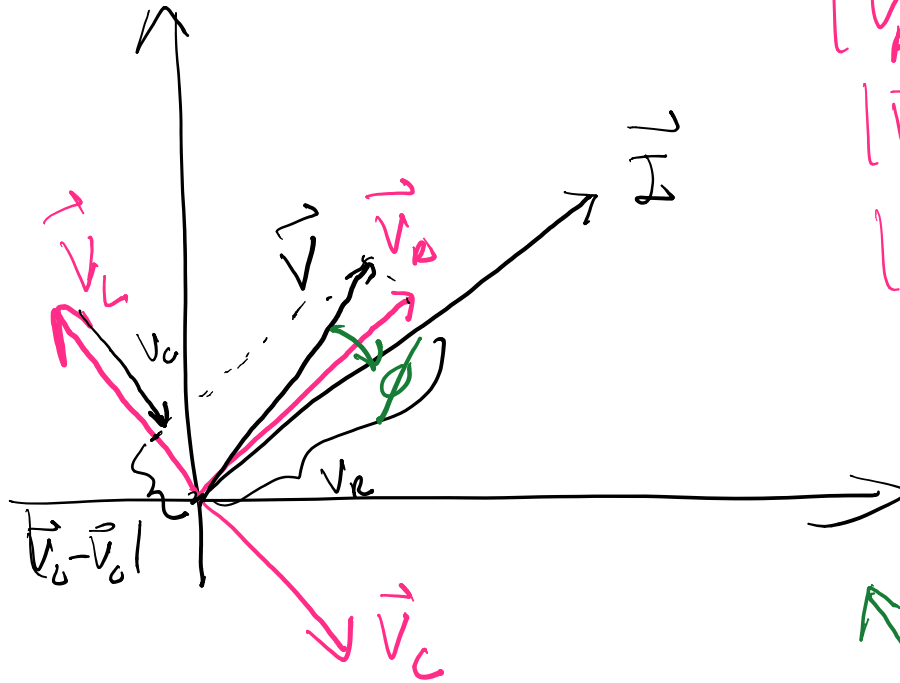
$$i_{RMS} = \frac{i_0}{\sqrt{2}}$$

↓
root mean square



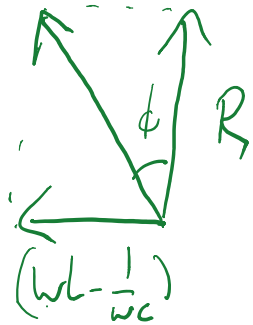
$(\sim) V(t) = V_0 \cos(\omega t)$

$\{ \begin{matrix} R \\ \omega L \\ \frac{1}{\omega C} \end{matrix} \}$



$|\vec{V}_R| = R i_0$
 $|\vec{V}_O| = \frac{1}{\omega C} i_0$
 $|\vec{V}_L| = \omega L i_0$

$\vec{V} = \vec{V}_R + \vec{V}_O + \vec{V}_L$



$V_0 = |\vec{V}| = \sqrt{R^2 i_0^2 + \left(\omega L - \frac{1}{\omega C}\right)^2 i_0^2}$

$\phi = \arctan\left(\frac{\omega L - \frac{1}{\omega C}}{R}\right)$

$i_0 = \frac{V_0}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}}$

$P = R i_0^2 = \frac{R V_0^2}{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}$

$$2 \quad 2 \left(R^2 + \left(\omega L - \frac{1}{\omega C} \right)^2 \right)$$

At which frequency is P maximum?

Clearly $\omega L = \frac{1}{\omega C}$

